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# Algebraic aspects of integrable nonlinear evolution equations with deep reductions 

## I. Equations on symmetric and homogeneous spaces

V. S. Gerdjikov

Institute for Nuclear Research and Nuclear Energy
Bulgarian Academy of Sciences
1784 Sofia, Bulgaria

## Based on:

- V. S. Gerdjikov. Algebraic and Analytic Aspects of $N$-wave Type Equations. Contemporary Mathematics 301, 35-68 (2002).
- V. S. Gerdjikov, D. J. Kaup, N. A. Kostov, T. I. Valchev. On classification of soliton solutions of multicomponent nonlinear evolution equations.
J. Phys. A: Math. Theor. 41 (2008) 315213 (36pp).
- Nikolay Kostov, Vladimir Gerdjikov. Reductions of multicomponent $m K d V$ equations on symmetric spaces of DIII-type. SIGMA 4 (2008), paper 029, 30 pages; ArXiv:0803.1651.
- V. S. Gerdjikov. Selected Aspects of Soliton Theory. Constant boundary conditions. In: Prof. G. Manev's Legacy in Contemporary Aspects of Astronomy, Gravitational and Theoretical Physics Eds.: V. Gerdjikov, M. Tsvetkov, Heron Press Ltd, Sofia, 2005. pp. 277-290. nlin.SI/0604004


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## 1 BEC with hyperfine structure

${ }^{23} \mathrm{Na} \Leftrightarrow F=1 \quad{ }^{87} \mathrm{Rb} \Leftrightarrow F=2$
see Wadati et al (2004), (2006), (2007); Ohmi \& Machida (1998);
Kuwamoto et al (2004); Gerdjikov et al (2007), (2008)
The assembly of atoms in the hyperfine state of spin $F$ is described by a normalized spinor wave vector with $2 F+1$ components

$$
\Phi(x, t)=\left(\Phi_{F}(x, t), \Phi_{F-1}(x, t), \ldots, \Phi_{-F}(x, t)\right)^{T}
$$

whose components are labeled by the values of $m_{F}=F, \ldots, 1,0,-1, \ldots,-F$.
GPE-equation in the one-dimensional approximation:

$$
\begin{equation*}
i \frac{\partial \Phi}{\partial t}=\frac{\delta E_{\mathrm{GP}}[\Phi]}{\delta \Phi^{*}} \tag{1}
\end{equation*}
$$

where for $F=1$ the energy functional is given by:

$$
E_{\mathrm{GP}}=\int d x\left\{\frac{\hbar^{2}}{2 m}\left|\partial_{x} \Phi\right|^{2}+\frac{\bar{c}_{0}+\bar{c}_{2}}{2}\left[\left|\Phi_{1}\right|^{4}+\left|\Phi_{-1}\right|^{4}+2\left|\Phi_{0}\right|^{2}\left(\left|\Phi_{1}\right|^{2}+\left|\Phi_{-1}\right|^{2}\right)\right]\right.
$$

$$
\begin{equation*}
\left.+\left(\bar{c}_{0}-\bar{c}_{2}\right)\left|\Phi_{1}\right|^{2}\left|\Phi_{-1}\right|^{2}+\frac{\bar{c}_{0}}{2}\left|\Phi_{0}\right|^{4}+\bar{c}_{2}\left(\Phi_{1}^{*} \Phi_{-1}^{*} \Phi_{0}^{2}+\Phi_{0}^{* 2} \Phi_{1} \Phi_{-1}\right)\right\} \tag{2}
\end{equation*}
$$

the effective 1D couplings $\bar{c}_{0,2}$ are represented by

$$
\begin{equation*}
\bar{c}_{0}=c_{0} / 2 a_{\perp}^{2}, \quad \bar{c}_{2}=c_{2} / 2 a_{\perp}^{2} \tag{3}
\end{equation*}
$$

where $a_{\perp}$ is the size of the transverse ground state. In this expression,

$$
\begin{equation*}
c_{0}=\pi \hbar^{2}\left(a_{0}+2 a_{2}\right) / 3 m, \quad c_{2}=\pi \hbar^{2}\left(a_{2}-a_{0}\right) / 3 m \tag{4}
\end{equation*}
$$

where $a_{f}$-s-wave scattering lengths; $m$ is the mass of the atom.
Special (integrable) choice for the coupling constants $\bar{c}_{0}=\bar{c}_{2} \equiv-c<$ 0 , equivalently scattering lengths $2 a_{0}=-a_{2}>0$. In the dimensionless form: $\Phi \rightarrow\left\{\Phi_{1}, \sqrt{2} \Phi_{0}, \Phi_{-1}\right\}^{T}$ the corresponding GPE take the form:

$$
\begin{align*}
& i \partial_{t} \Phi_{1}+\partial_{x}^{2} \Phi_{1}+2\left(\left|\Phi_{1}\right|^{2}+2\left|\Phi_{0}\right|^{2}\right) \Phi_{1}+2 \Phi_{-1}^{*} \Phi_{0}^{2}=0 \\
& i \partial_{t} \Phi_{0}+\partial_{x}^{2} \Phi_{0}+2\left(\left|\Phi_{-1}\right|^{2}+\left|\Phi_{0}\right|^{2}+\left|\Phi_{1}\right|^{2}\right) \Phi_{0}+2 \Phi_{0}^{*} \Phi_{1} \Phi_{-1}=0  \tag{5}\\
& i \partial_{t} \Phi_{-1}+\partial_{x}^{2} \Phi_{-1}+2\left(\left|\Phi_{-1}\right|^{2}+2\left|\Phi_{0}\right|^{2}\right) \Phi_{-1}+2 \Phi_{1}^{*} \Phi_{0}^{2}=0
\end{align*}
$$

$F=2$ hyperfine state is described by a normalized spinor wave vector

$$
\begin{equation*}
\Phi(x, t)=\left(\Phi_{2}(x, t), \Phi_{1}(x, t), \Phi_{0}(x, t), \Phi_{-1}(x, t), \Phi_{-2}(x, t)\right)^{T} \tag{6}
\end{equation*}
$$

whose components are labelled by the values of $m_{F}=2,1,0,-1,-2$. Here the energy functional within mean-field theory is defined by

$$
\begin{equation*}
E_{\mathrm{GP}}[\Phi]=\int_{-\infty}^{\infty} d x\left(\frac{\hbar^{2}}{2 m}\left|\partial_{x} \Phi\right|^{2}+\frac{\epsilon c_{0}}{2} n^{2}+\frac{c_{2}}{2} \mathbf{f}^{2}+\frac{\epsilon c_{4}}{2}|\Theta|^{2}\right) \tag{7}
\end{equation*}
$$

where $\epsilon= \pm 1$. The number density and the singlet-pair amplitude are defined by

$$
n=\left(\vec{\Phi}, \overrightarrow{\Phi^{*}}\right)=\sum_{\alpha=-2}^{2} \Phi_{\alpha} \Phi_{\alpha}^{*}, \quad \Theta=\left(\vec{\Phi}, s_{0} \vec{\Phi}\right)=2 \Phi_{2} \Phi_{-2}-2 \Phi_{1} \Phi_{-1}+\Phi_{0}^{2}
$$

The coupling constants $c_{i}$ are real and can be expressed in terms of the transverse confinement radius and the $s$-wave scattering lengths of atoms. Choosing $c_{2}=0, c_{4}=1$ and $c_{0}=-2$ we obtain

$$
i \partial_{t} \Phi_{ \pm 2}+\partial_{x x} \Phi_{ \pm 2}=-2 \epsilon\left(\vec{\Phi}, \overrightarrow{\Phi^{*}}\right) \Phi_{ \pm 2}+\epsilon\left(2 \Phi_{2} \Phi_{-2}-2 \Phi_{1} \Phi_{-1}+\Phi_{0}^{2}\right) \Phi_{\mp 2}^{*}
$$

$$
\begin{aligned}
& i \partial_{t} \Phi_{ \pm 1}+\partial_{x x} \Phi_{ \pm 1}=-2 \epsilon\left(\vec{\Phi}, \overrightarrow{\Phi^{*}}\right) \Phi_{ \pm 1}-\epsilon\left(2 \Phi_{2} \Phi_{-2}-2 \Phi_{1} \Phi_{-1}+\Phi_{0}^{2}\right) \Phi_{\mp 1}^{*} \\
& i \partial_{t} \Phi_{0}+\partial_{x x} \Phi_{0}=-2 \epsilon\left(\vec{\Phi}, \overrightarrow{\Phi^{*}}\right) \Phi_{ \pm 0}+\epsilon\left(2 \Phi_{2} \Phi_{-2}-2 \Phi_{1} \Phi_{-1}+\Phi_{0}^{2}\right) \Phi_{0}^{*}
\end{aligned}
$$

which is integrable by the inverse scattering method.
Lax pair is related to symmetric spaces Fordy, Kulish (1983) of BD.Itype:

$$
\simeq \mathrm{SO}(\mathrm{n}+2) / \mathrm{SO}(2) \times \mathrm{SO}(\mathrm{n})
$$

with $n=3$ and $n=5$ respectively.

## 2 Symmetric and homogeneous spaces

Symmetric space: $\mathcal{M}$ is globally symmetric if each its point $p$ is isolated invariant point under an involutive isometry:

$$
\mathcal{K}(\mathcal{N})=\mathcal{M}, \quad \mathcal{K}^{2}=\mathbb{1}
$$

Cartan has classified all such involutions.
$\mathcal{M} \equiv \mathfrak{G} / \mathcal{H}$ where $\mathfrak{G}$ is simple and $\mathcal{H}$ is semisimple. Normally

$$
\mathcal{H} \equiv\left\{K \in \mathfrak{G}, \quad \text { such that } \quad K J K^{-1}=J, \quad J \in \mathcal{H}\right\} .
$$

Local coordinates:

$$
Q(x)=\left[J, Q^{\prime}(x)\right] .
$$

Typically

$$
J=\left(\begin{array}{cc}
\mathbb{1} & 0 \\
0 & -\mathbb{1}
\end{array}\right), \quad Q(x)=\left(\begin{array}{cc}
0 & Q^{+}(x) \\
Q^{-}(x) & 0
\end{array}\right),
$$

But for BD.I-type symmetric spaces:

$$
J=\left(\begin{array}{ccc}
1 & 0 & 0 \\
0 & 0 & 0 \\
0 & 0 & -1
\end{array}\right), \quad Q=\left(\begin{array}{ccc}
0 & \vec{q}^{T} & 0 \\
\vec{p} & 0 & s_{0} \vec{q} \\
0 & \vec{p}^{T} s_{0} & 0
\end{array}\right)
$$

Effectively it is enough to properly specify $\mathfrak{G}$ and $J$ in order to determine $\mathcal{M}$. The corresponding Lie algebra $\mathfrak{g}$ acquires $\mathbb{Z}_{2}$-grading:

$$
\mathfrak{g}=\mathfrak{g}^{(0)}+\mathfrak{g}^{(1)}
$$

$$
\mathfrak{g}^{(0)} \equiv\{X: X \in \mathfrak{g} \quad \mathcal{K}(X)=X\}, \quad \mathfrak{g}^{(1)} \equiv\{X: X \in \mathfrak{g} \quad \mathcal{K}(Y)=-Y\},
$$

The grading property:

$$
\left[\mathfrak{g}^{(0)}, \mathfrak{g}^{(0)}\right] \in \mathfrak{g}^{(0)}, \quad\left[\mathfrak{g}^{(0)}, \mathfrak{g}^{(1)}\right] \in \mathfrak{g}^{(1)}, \quad\left[\mathfrak{g}^{(1)}, \mathfrak{g}^{(1)}\right] \in \mathfrak{g}^{(0)}
$$

The set of positive roots $\Delta^{+}$also splits into two subsets:

$$
\begin{gathered}
\Delta^{+}=\Delta_{0}^{+} \cup \Delta_{1}^{+} \\
\Delta_{0}^{+} \equiv\{\alpha: \quad \alpha(J)=0\} \quad \Delta_{1}^{+} \equiv\{\alpha: \quad \alpha(J)=a>0\}
\end{gathered}
$$

## 3 Multicomponent nonlinear Schrödinger equations for BD.I. series of symmetric spaces

MNLS equations for the BD.I. series of symmetric spaces (algebras of the type $s o(2 r+1)$ and $J$ dual to $e_{1}$ ) have the Lax representation $[L, M]=0$ as follows

$$
\begin{equation*}
L \psi(x, t, \lambda) \equiv i \partial_{x} \psi+(Q(x, t)-\lambda J) \psi(x, t, \lambda)=0 . \tag{8}
\end{equation*}
$$

$$
\begin{align*}
& M \psi(x, t, \lambda) \equiv i \partial_{t} \psi+\left(V_{0}(x, t)+\lambda V_{1}(x, t)-\lambda^{2} J\right) \psi(x, t, \lambda)=0,  \tag{9}\\
& V_{1}(x, t)=Q(x, t), \quad V_{0}(x, t)=i \operatorname{ad}_{J}^{-1} \frac{d Q}{d x}+\frac{1}{2}\left[\operatorname{ad}_{J}^{-1} Q, Q(x, t)\right](10)
\end{align*}
$$

where

$$
Q=\left(\begin{array}{ccc}
0 & \vec{q}^{T} & 0  \tag{11}\\
\vec{p} & 0 & s_{0} \vec{q} \\
0 & \vec{p}^{T} s_{0} & 0
\end{array}\right), \quad J=\operatorname{diag}(1,0, \ldots 0,-1)
$$

The $2 r-1$-vectors $\vec{q}$ and $\vec{p}$ have the form

$$
\vec{q}=\left(q_{2}, \ldots, q_{r}, q_{r+1}, q_{r+2}, \ldots, q_{2 r}\right)^{T}, \quad \vec{p}=\left(p_{2}, \ldots, p_{r}, p_{r+1}, p_{r+2}, \ldots, p_{2 r}\right)^{T}
$$

while the matrix $s_{0}$ represents the metric involved in the definition of $s o(2 r-1)$, therefore it is related to the metric $S_{0}$ associated with so $(2 r+$ 1) in the following manner

$$
S_{0}=\sum_{k=1}^{2 r+1}(-1)^{k+1} E_{k, 2 r+2-k}=\left(\begin{array}{ccc}
0 & 0 & 1 \\
0 & -s_{0} & 0 \\
1 & 0 & 0
\end{array}\right), \quad\left(E_{k n}\right)_{i j}=\delta_{i k} \delta_{n j}(12)
$$

Next we will use

$$
\begin{equation*}
\vec{E}_{1}^{ \pm}=\left(E_{ \pm\left(e_{1}-e_{2}\right)}, \ldots, E_{ \pm\left(e_{1}-e_{r}\right)}, E_{ \pm e_{1}}, E_{ \pm\left(e_{1}+e_{r}\right)}, \ldots, E_{ \pm\left(e_{1}+e_{2}\right)}\right), \tag{13}
\end{equation*}
$$

We will use also the "scalar product"

$$
\left(\vec{q} \cdot \vec{E}_{1}^{+}\right)=\sum_{k=2}^{r}\left(q_{k}(x, t) E_{e_{1}-e_{k}}+q_{2 r-k+2}(x, t) E_{e_{1}+e_{k}}\right)+q_{r+1}(x, t) E_{e_{1}}
$$

Then the generic form of the potentials $Q(x, t)$ related to these type of symmetric spaces is

$$
\begin{equation*}
Q(x, t)=\left(\vec{q}(x, t) \cdot \vec{E}_{1}^{+}\right)+\left(\vec{p}(x, t) \cdot \vec{E}_{1}^{-}\right), \tag{14}
\end{equation*}
$$

where $E_{\alpha}$ are the Weyl generators of the corresponding Lie algebra and $\Delta_{1}^{+}$is the set of all positive roots of $s o(2 r+1)$ such that $\left(\alpha, e_{1}\right)=1$. In fact $\Delta_{1}^{+}=\left\{e_{1}, \quad e_{1} \pm e_{k}, \quad k=2, \ldots, r\right\}$.

In terms of these notations the generic MNLS type equations connected to BD.I. acquire the form

$$
\begin{align*}
& i \vec{q}_{t}+\vec{q}_{x x}+2(\vec{q}, \vec{p}) \vec{q}-\left(\vec{q}, s_{0} \vec{q}\right) s_{0} \vec{p}=0  \tag{15}\\
& i \vec{p}_{t}-\vec{p}_{x x}-2(\vec{q}, \vec{p}) \vec{p}+\left(\vec{p}, s_{0} \vec{p}\right) s_{0} \vec{q}=0
\end{align*}
$$

In the case of $r=2$ if we impose the reduction $p_{k}=q_{k}^{*}$ and introduce the new variables $\Phi_{1}=q_{2}, \Phi_{0}=q_{3} / \sqrt{2}, \Phi_{-1}=q_{4}$ then we reproduce the equations (119) with $F=1$; if $\Phi_{2}=q_{2}, \Phi_{1}=q_{3}, \Phi_{0}=q_{4}, \Phi_{-1}=q_{5}$, $\Phi_{-2}=q_{6}$ then we get the $F=2$-case.

## 4 Inverse scattering method and reconstruction of potential from minimal scattering data

Herein we remind some basic features of the inverse scattering theory appropriate for the special case of $F=2$ spinor BEC equations.

Solving the direct and the inverse scattering problem (ISP) for $L$ uses the Jost solutions

$$
\begin{equation*}
\lim _{x \rightarrow-\infty} \phi(x, t, \lambda) e^{i \lambda J x}=\mathbb{1}, \quad \lim _{x \rightarrow \infty} \psi(x, t, \lambda) e^{i \lambda J x}=\mathbb{1} \tag{16}
\end{equation*}
$$

and the scattering matrix $T(\lambda, t) \equiv \psi^{-1} \phi(x, t, \lambda)$. Due to the special choice of $J$ and to the fact that the Jost solutions and the scattering matrix take values in the group $S O(2 r+1)$ we can use the following
block-matrix structure of $T(\lambda, t)$

$$
T(\lambda, t)=\left(\begin{array}{ccc}
m_{1}^{+} & -\vec{b}^{-T} & c_{1}^{-}  \tag{17}\\
\vec{b}^{+} & \mathbf{T}_{22} & -s_{0} \vec{B}^{-} \\
c_{1}^{+} & \vec{B}^{+T} s_{0} & m_{1}^{-}
\end{array}\right),
$$

where $\vec{b}^{ \pm}(\lambda, t)$ and $\vec{B}^{ \pm}(\lambda, t)$ are $2 r$ - 1-component vectors, $\mathbf{T}_{22}(\lambda)$ is a $2 r-1 \times 2 r-1$ block and $m_{1}^{ \pm}(\lambda), c_{1}^{ \pm}(\lambda)$ are scalar functions satisfying $c_{1}^{+}=1 / 2\left(\vec{b}^{+} \cdot s_{0} \vec{b}^{+}\right) / m_{1}^{+}, c_{1}^{-}=1 / 2\left(\vec{B}^{-} \cdot s_{0} \vec{B}^{-}\right) / m_{1}^{-}$.

The ISP is reduced to a Riemann-Hilbert problem (RHP) for the fundamental analytic solution (FAS) $\chi^{ \pm}(x, t, \lambda)$. Their construction is based on the generalized Gauss decomposition of $T(\lambda, t)$

$$
\begin{equation*}
T(\lambda)=T_{J}^{-}(\lambda) D_{J}^{+}(\lambda) \hat{S}_{J}^{+}(\lambda)=T_{J}^{+}(\lambda) D_{J}^{-}(\lambda) \hat{S}_{J}^{-}(\lambda) \tag{18}
\end{equation*}
$$

Here $S_{J}^{ \pm}, T_{J}^{ \pm}$upper- and lower-block-triangular matrices, while $D_{J}^{ \pm}(\lambda)$ are block-diagonal matrices with the same block structure as $T(\lambda, t)$ above. The explicit expressions of the Gauss factors in terms of the
matrix elements of $T(\lambda, t)$ is

$$
\begin{align*}
& \left.S_{J}^{ \pm}(t, \lambda)=\exp \left( \pm\left(\vec{\tau}^{ \pm}(\lambda, t) \cdot \vec{E}_{1}^{ \pm}\right)\right), \quad \tau^{+}=\frac{b^{-}}{m_{1}^{+}}, \quad \tau^{-}=\frac{B_{1}^{+}}{m_{1}^{-}} 19\right) \\
& T_{J}^{ \pm}(t, \lambda)=\exp \left(\mp\left(\vec{\rho}^{\mp}(\lambda, t) \cdot \vec{E}_{1}^{ \pm}\right)\right), \quad \rho^{+}=\frac{b^{+}}{m_{1}^{+}}, \quad \rho^{-}=\frac{B_{1}^{-}}{m_{1}^{-}}, \\
& D_{J}^{+}=\left(\begin{array}{ccc}
m_{1}^{+} & 0 & 0 \\
0 & \mathbf{m}_{2}^{+} & 0 \\
0 & 0 & 1 / m_{1}^{+}
\end{array}\right), \quad D_{J}^{-}=\left(\begin{array}{ccc}
1 / m_{1}^{-} & 0 & 0 \\
0 & \mathbf{m}_{2}^{-} & 0 \\
0 & 0 & m_{1}^{-}
\end{array}\right), \tag{20}
\end{align*}
$$

and

$$
\mathbf{m}_{2}^{+}=\mathbf{T}_{22}+\frac{\vec{b}^{+} \vec{b}^{-T}}{m_{1}^{+}}, \quad \mathbf{m}_{2}^{-}=\mathbf{T}_{22}+\frac{s_{0} \vec{b}^{-} \vec{b}^{+T} s_{0}}{m_{1}^{-}}
$$

Then the FAS can be defined as:

$$
\begin{equation*}
\chi^{ \pm}(x, t, \lambda)=\phi(x, t, \lambda) S_{J}^{ \pm}(t, \lambda)=\psi(x, t, \lambda) T_{J}^{\mp}(t, \lambda) D_{J}^{ \pm}(\lambda) \tag{21}
\end{equation*}
$$

If $Q(x, t)$ evolves according to (119) then the scattering matrix and
its elements satisfy the following linear evolution equations

$$
\begin{align*}
& i \frac{d \vec{b}^{ \pm}}{d t} \pm \lambda^{2} \vec{b}^{ \pm}(t, \lambda)=0, \quad i \frac{d \vec{B}^{ \pm}}{d t} \pm \lambda^{2} \vec{B}^{ \pm}(t, \lambda)=0 \\
& i \frac{d m_{1}^{ \pm}}{d t}=0, \quad i \frac{d \mathbf{m}_{2}^{ \pm}}{d t}=0 \tag{22}
\end{align*}
$$

so $D^{ \pm}(\lambda)$ can be considered as generating functionals of the integrals of motion.

The FAS for real $\lambda$ are linearly related

$$
\begin{equation*}
\chi^{+}(x, t, \lambda)=\chi^{-}(x, t, \lambda) G_{J}(\lambda, t), \quad G_{0, J}(\lambda, t)=S_{J}^{-}(\lambda, t) S_{J}^{+}(\lambda, t) \tag{23}
\end{equation*}
$$

One can rewrite eq. (23) in an equivalent form for the $\operatorname{FAS} \xi^{ \pm}(x, t, \lambda)=$ $\chi^{ \pm}(x, t, \lambda) e^{i \lambda J x}$ which satisfy also the relation

$$
\begin{equation*}
\lim _{\lambda \rightarrow \infty} \xi^{ \pm}(x, t, \lambda)=\mathbb{1} \tag{24}
\end{equation*}
$$

Then these FAS satisfy

$$
\begin{equation*}
\xi^{+}(x, t, \lambda)=\xi^{-}(x, t, \lambda) G_{J}(x, \lambda, t), \quad G_{J}(x, \lambda, t)=e^{-i \lambda J x} G_{0, J}^{-}(\lambda, t) e^{i \lambda J x} \tag{25}
\end{equation*}
$$

Obviously the sewing function $G_{j}(x, \lambda, t)$ is uniquely determined by the Gauss factors $S_{J}^{ \pm}(\lambda, t)$. In view of eq. (19) we arrive to the following

Lemma 1. Let the potential $Q(x, t)$ be such that the Lax operator $L$ has no discrete eigenvalues. Then as minimal set of scattering data which determines uniquely the scattering matrix $T(\lambda, t)$ and the corresponding potential $Q(x, t)$ one can consider either one of the sets $\mathfrak{T}_{i}, i=1,2$
$\mathfrak{T}_{1} \equiv\left\{\vec{\rho}^{+}(\lambda, t), \vec{\rho}(\lambda, t), \quad \lambda \in \mathbb{R}\right\}, \quad \mathfrak{T}_{2} \equiv\left\{\vec{\tau}^{+}(\lambda, t), \vec{\tau}^{-}(\lambda, t), \quad \lambda \in \mathbb{R}\right\}$.

Obviously, given $\mathfrak{T}_{i}$ one uniquely recovers the sewing function $G_{J}(x, t, \lambda)$. In order to recover the corresponding scattering matrix $T(\lambda)$ one can use the fact that the RHP (25) with canonical normalization has unique regular solution. Then the generalized Gauss factors are recovered as limits:

$$
\begin{equation*}
S_{J}^{ \pm}(\lambda)=\lim _{x \rightarrow-\infty} e^{i \lambda J x} \xi^{ \pm}(x, \lambda) e^{-i \lambda J x}, \quad T_{j}^{\mp}(\lambda) D_{J}^{ \pm}(\lambda)=\lim _{x \rightarrow \infty} e^{i \lambda J x} \xi^{ \pm}(x, \lambda) e^{-i \lambda J x} \tag{27}
\end{equation*}
$$

Given the solution $\xi^{ \pm}(x, t, \lambda)$ one recovers $Q(x, t)$ via the formula

$$
\begin{equation*}
Q(x, t)=\lim _{\lambda \rightarrow \infty} \lambda\left(J-\xi^{ \pm} J \widehat{\xi}^{ \pm}(x, t, \lambda)\right) \tag{28}
\end{equation*}
$$

We impose also the standard reduction:

$$
Q(x, t)=\epsilon Q^{\dagger}(x, t) \Leftrightarrow p_{k}=\epsilon q_{k}^{*}
$$

As a consequence we have

$$
\vec{\rho}^{-}(\lambda, t)=\epsilon \vec{\rho}^{+, *}(\lambda, t), \quad \vec{\tau}^{-}(\lambda, t)=\epsilon \overrightarrow{\mathcal{T}}^{+, *}(\lambda, t)
$$

## 5 Dressing method and soliton solutions

The soliton solutions can be constructed by Hirota method (Wadati, (2005)) and also by the dressing Zakharov-Shabat method (VSG et al, (2006).

The main goal of the Zakharov-Shabat dressing method: starting from a known solutions $\chi_{0}^{ \pm}(x, t, \lambda)$ of $L_{0}(\lambda)$ with potential $Q_{(0)}(x, t)$
to construct new singular solutions $\chi_{1}^{ \pm}(x, t, \lambda)$ of $L$ with a potential $Q_{(1)}(x, t)$ with two additional singularities located at prescribed positions $\lambda_{1}^{ \pm}$; the reduction $\vec{p}=\vec{q}^{*}$ ensures that $\lambda_{1}^{-}=\left(\lambda_{1}^{+}\right)^{*}$. It is related to the regular one by a dressing factor $u(x, t, \lambda)$

$$
\begin{equation*}
\chi_{1}^{ \pm}(x, t, \lambda)=u(x, \lambda) \chi_{0}^{ \pm}(x, t, \lambda) u_{-}^{-1}(\lambda) . \quad u_{-}(\lambda)=\lim _{x \rightarrow-\infty} u(x, \lambda) \tag{29}
\end{equation*}
$$

Note that $u_{-}(\lambda)$ is a block-diagonal matrix. $u(x, \lambda)$ must satisfy

$$
\begin{equation*}
i \partial_{x} u+Q_{(1)}(x) u-u Q_{(0)}(x)-\lambda[J, u(x, \lambda)]=0 \tag{30}
\end{equation*}
$$

and the normalization condition $\lim _{\lambda \rightarrow \infty} u(x, \lambda)=\mathbb{1}$.
The construction of $u(x, \lambda)$ is based on an appropriate anzats specifying explicitly the form of its $\lambda$-dependence:
$u(x, \lambda)=\mathbb{1}+(c(\lambda)-1) P(x, t)+\left(\frac{1}{c(\lambda)}-1\right) \bar{P}(x, t), \quad \bar{P}=S_{0}^{-1} P^{T} S_{0}$,
where $P(x, t)$ and $\bar{P}(x, t)$ are projectors whose rank $s$ can not exceed $r$ and which satisfy $P \bar{P}(x, t)=0$. Given a set of $s$ linearly independent
polarization vectors $\left|n_{k}\right\rangle$ spanning the corresponding eigensubspase of $L$ one can define

$$
\begin{align*}
& P(x, t)=\sum_{a, b=1}^{s}\left|n_{a}(x, t)\right\rangle M_{a b}^{-1}\left\langle n_{b}^{\dagger}(x, t)\right|, \quad M_{a b}(x, t)=\left\langle n_{b}^{\dagger}(x, t) \mid n_{a}(x, t)\right\rangle, \\
& \left|n_{a}(x, t)\right\rangle=\chi_{0}^{+}\left(x, t, \lambda^{+}\right)\left|n_{0, a}\right\rangle, \quad c(\lambda)=\frac{\lambda-\lambda^{+}}{\lambda-\lambda^{-}}, \quad\left\langle n_{0, a}\right| S_{0}\left|n_{0, b}\right\rangle=0 \tag{32}
\end{align*}
$$

Taking the limit $\lambda \rightarrow \infty$ in eq. (30) we get that

$$
Q_{(1)}(x, t)-Q_{(0)}(x, t)=\left(\lambda_{1}^{-}-\lambda_{1}^{+}\right)[J, P(x, t)-\bar{P}(x, t)] .
$$

Below we list the explicit expressions only for the one-soliton solutions. To this end we assume $Q_{(0)}=0$ and put $\lambda_{1}^{ \pm}=\mu \pm i \nu$. As a result we get

$$
\begin{equation*}
q_{k}^{(1 \mathrm{~s})}(x, t)=-2 i \nu\left(P_{1 k}(x, t)+(-1)^{k} P_{\bar{k}, 2 r+1}(x, t)\right), \tag{33}
\end{equation*}
$$

where $\bar{k}=2 r+2-k$.
Repeating the above procedure $N$ times we can obtain $N$ soliton solutions.

### 5.1 The case of rank one solitons

In this case $s=1$ so that the generic (arbitrary $r$ ) one-soliton solution reads

$$
\begin{align*}
q_{k} & =\frac{-i \nu e^{-i \mu\left(x-v t-\delta_{0}\right)}}{\cosh 2 z+\Delta_{0}^{2}}\left(\alpha_{k} e^{z-i \phi_{k}}+(-1)^{k} \alpha_{\bar{k}} e^{-z+i \phi_{\bar{k}}}\right) \\
v & =\frac{\nu^{2}-\mu^{2}}{\mu}, \quad u=-2 \mu, \quad z(x, t)=\nu\left(x-u t-\xi_{0}\right)  \tag{34}\\
\xi_{0} & =\frac{1}{2 \nu} \ln \frac{\left|n_{0,2 r+1}\right|}{\left|n_{0,1}\right|}, \quad \alpha_{k}=\frac{\left|n_{0, k}\right|}{\sqrt{\left|n_{0,1}\right|\left|n_{0,2 r+1}\right|}}, \quad \Delta_{0}^{2}=\frac{\sum_{k=2}^{2 r}\left|n_{0, k}\right|^{2}}{2\left|n_{0,1} n_{0,2 r+1}\right|}
\end{align*}
$$

and $\delta_{0}=\arg n_{0,1} / \mu=-\arg n_{0,2 r+1} / \mu, \phi_{k}=\arg n_{0, k}$. The polarization vectors satisfy the following relation

$$
\begin{equation*}
\sum_{k=1}^{r} 2(-1)^{k+1} n_{0, k} n_{0, \bar{k}}+(-1)^{r} n_{0, r+1}^{2}=0 \tag{35}
\end{equation*}
$$

Thus for $r=2$ we identify $\Phi_{1}=q_{2}, \Phi_{0}=q_{3} / \sqrt{2}$ and $\Phi_{3}=q_{4}$ and we obtain the following solutions for the equation (119)

$$
\begin{aligned}
\Phi_{ \pm 1} & =-\frac{2 i \nu \sqrt{\alpha_{2} \alpha_{4}} e^{-i \mu\left(x-v t-\delta_{ \pm 1}\right)}}{\cosh 2 z+\Delta_{0}^{2}}\left(\cos \phi_{ \pm 1} \cosh z_{ \pm 1}-i \sin \phi_{ \pm 1} \sinh z_{ \pm 1}\right) \\
\delta_{ \pm 1} & =\delta_{0} \mp \frac{\phi_{2}-\phi_{4}}{2 \mu}, \quad \phi_{ \pm 1}=\frac{\phi_{2}+\phi_{4}}{2} \quad z_{ \pm 1}=z \mp \frac{1}{2} \ln \frac{\alpha_{4}}{\alpha_{2}} \\
\Phi_{0} & =-\frac{\sqrt{2} i \nu \alpha_{3} e^{-i \mu\left(x-v t-\delta_{0}\right)}}{\cosh 2 z+\Delta_{0}^{2}}\left(\cos \phi_{3} \sinh z-i \sin \phi_{3} \cosh z\right)
\end{aligned}
$$

For $r=3$ we identify $\Phi_{2}=q_{2}, \Phi_{1}=q_{3}, \Phi_{0}=q_{4}, \Phi_{-1}=q_{5}$ and $\Phi_{-2}=q_{6}$, so that the one-soliton solution for equation (??) reads

$$
\begin{aligned}
& \Phi_{ \pm 2}=-\frac{2 i \nu \sqrt{\alpha_{2} \alpha_{6}} e^{-i \mu\left(x-v t-\delta_{ \pm 2}\right)}}{\cosh 2 z+\Delta_{0}^{2}}\left(\cos \phi_{ \pm 2} \cosh z_{ \pm 2}-i \sin \phi_{ \pm 2} \sinh z_{ \pm 2}\right) \\
& \Phi_{ \pm 1}=-\frac{2 i \nu \sqrt{\alpha_{3} \alpha_{5}} e^{-i \mu\left(x-v t-\delta_{ \pm 1}\right)}}{\cosh 2 z+\Delta_{0}^{2}}\left(\cos \phi_{ \pm 1} \sinh z_{ \pm 1}-i \sin \phi_{ \pm 1} \cosh z_{ \pm 1}\right) \\
& \delta_{ \pm 2}=\delta_{0} \mp \frac{\phi_{2}-\phi_{6}}{2 \mu}, \quad \phi_{ \pm 2}=\frac{\phi_{2}+\phi_{6}}{2} \quad z_{ \pm 2}=z \mp \frac{1}{2} \ln \frac{\alpha_{6}}{\alpha_{2}}
\end{aligned}
$$

$$
\begin{aligned}
\delta_{ \pm 1} & =\delta_{0} \mp \frac{\phi_{3}-\phi_{5}}{2 \mu}, \quad \phi_{ \pm 1}=\frac{\phi_{3}+\phi_{5}}{2}, \quad z_{ \pm 1}=z \mp \frac{1}{2} \ln \frac{\alpha_{5}}{\alpha_{3}} \\
\Phi_{0} & =-\frac{2 i \nu \alpha_{4} e^{-i \mu\left(x-v t-\delta_{0}\right)}}{\cosh 2 z+\Delta_{0}^{2}}\left(\cos \phi_{4} \cosh z-i \sin \phi_{4} \sinh z\right) .
\end{aligned}
$$

Choosing appropriately the polarization vectors $|n\rangle$ we are able to reproduce the soliton solutions obtained by Wadati et al. both for $F=1$ and $F=2$ BEC.

## 6 Effects of reductions on soliton solutions

The reduction group $G_{R}$ (Mikhailov, 1978) is a finite group which preserves the Lax representation so that the reduction constraints are automatically compatible with the evolution.
$G_{R}$ must have two realizations:
i) $G_{R} \subset$ Autg and
ii) $G_{R} \subset \operatorname{Conf} \mathbb{C}$, i.e. as conformal mappings of the complex $\lambda$-plane. To
each $g_{k} \in G_{R}$ we relate a reduction condition for the Lax pair:

$$
\begin{equation*}
U(x, t, \lambda)=[J, Q(x, t)]-\lambda J, \quad V(x, t, \lambda)=[I, Q(x, t)]-\lambda I \tag{36}
\end{equation*}
$$

of the Lax representation:
1)

$$
C_{1}\left(U^{\dagger}\left(\kappa_{1}(\lambda)\right)\right)=U(\lambda)
$$

$$
C_{1}\left(V^{\dagger}\left(\kappa_{1}(\lambda)\right)\right)=V(\lambda)
$$

$$
C_{2}\left(V^{T}\left(\kappa_{2}(\lambda)\right)\right)=-V(\lambda)
$$

$$
C_{3}\left(U^{*}\left(\kappa_{1}(\lambda)\right)\right)=-U(\lambda)
$$

$$
C_{3}\left(V^{*}\left(\kappa_{1}(\lambda)\right)\right)=-V(\lambda),
$$

$$
C_{4}\left(U\left(\kappa_{2}(\lambda)\right)\right)=U(\lambda),
$$

$$
C_{4}\left(V\left(\kappa_{2}(\lambda)\right)\right)=V(\lambda)
$$

### 6.1 N -wave system related to $s o(5)$

Impose first a reductions of class 4 that does not affect the spectral parameter. Choose $C_{2}=S_{0}, \kappa_{2}(\lambda)=\lambda$, so

$$
S_{0}\left(U^{T}(\lambda)\right) S_{0}^{-1}+U(\lambda)=0, \quad S_{0}=\left(\begin{array}{ccccc}
0 & 0 & 0 & 0 & 1 \\
0 & 0 & 0 & -1 & 0 \\
0 & 0 & 1 & 0 & 0 \\
0 & -1 & 0 & 0 & 0 \\
1 & 0 & 0 & 0 & 0
\end{array}\right)
$$

Focus our attention on NLEE related to the so(5) algebra. Thus the $N$-wave system itself consists of 8 equations. A half of them reads

$$
\begin{align*}
i\left(J_{1}-J_{2}\right) Q_{10, t}(x, t)-i\left(I_{1}-I_{2}\right) Q_{10, x}(x, t)+k Q_{11}(x, t) Q_{\overline{01}}(x, t) & =0 \\
i J_{1} Q_{11, t}(x, t)-i I_{1} Q_{11, x}(x, t)-k\left(Q_{10} Q_{01}+Q_{12} Q_{\overline{01}}\right)(x, t) & =0 \\
i\left(J_{1}+J_{2}\right) Q_{12, t}(x, t)-i\left(I_{1}+I_{2}\right) Q_{12, x}(x, t)-k Q_{11}(x, t) Q_{01}(x, t) & =0 \\
i J_{2} Q_{01, t}(x, t)-i I_{2} Q_{01, x}(x, t)+k\left(Q_{\overline{11}} Q_{12}+Q_{\overline{10}} Q_{11}\right)(x, t) & =0 \tag{37}
\end{align*}
$$

where $k:=J_{1} I_{2}-J_{2} I_{1}$ is a constant describing the wave interaction. The other 4 can be obtained by changing $Q_{k n} \leftrightarrow Q_{\overline{k n}}$. Dressing factor:

$$
\begin{gather*}
u(x, \lambda)=\mathbb{1}+(c(\lambda)-1) P(x)+\left(\frac{1}{c(\lambda)}-1\right) \bar{P}(x) \in S O(5)  \tag{38}\\
\bar{P}(x)=S_{0} P^{T}(x) S_{0}^{-1}
\end{gather*}
$$

Generic 1-soliton solution reads

$$
\begin{aligned}
Q_{10}(z) & =\frac{\lambda^{-}-\lambda^{+}}{\langle m \mid n\rangle}\left(e^{-i\left(\lambda^{+} z_{1}-\lambda^{-} z_{2}\right)} n_{0,1} m_{0,2}+e^{i\left(\lambda^{+} z_{2}-\lambda^{-} z_{1}\right)} n_{0,4} m_{0,5}\right) \\
Q_{11}(z) & =\frac{\lambda^{-}-\lambda^{+}}{\langle m \mid n\rangle}\left(e^{-i \lambda^{+} z_{1}} n_{0,1} m_{0,3}-e^{-i \lambda^{-} z_{1}} n_{0,3} m_{0,5}\right) \\
Q_{12}(z) & =\frac{\lambda^{-}-\lambda^{+}}{\langle m \mid n\rangle}\left(e^{-i\left(\lambda^{+} z_{1}+\lambda^{-} z_{2}\right)} n_{0,1} m_{0,4}+e^{-i\left(\lambda^{-} z_{1}+\lambda^{+} z_{2}\right)} n_{0,2} m_{0,5}\right), \\
Q_{01}(z) & =\frac{\lambda^{-}-\lambda^{+}}{\langle m \mid n\rangle}\left(e^{-i \lambda^{+} z_{2}} n_{0,2} m_{0,3}+e^{-i \lambda^{-} z_{2}} n_{0,3} m_{0,4}\right), \\
\langle m \mid n\rangle & =\sum_{k=1}^{5} e^{-i\left(\lambda^{+}-\lambda^{-}\right) z_{k}} n_{0, k} m_{0, k}, \quad z_{k}=J_{k} x+I_{k} t, \quad k=1,2 .
\end{aligned}
$$

The other 4 field can be formally constructed by doing the following transformation

$$
Q_{k n} \leftrightarrow Q_{\overline{k n}}, \quad e^{-i \lambda^{+} z_{k}} \leftrightarrow e^{i \lambda^{-} z_{k}}, \quad n_{0, j} \leftrightarrow m_{0, j}
$$

A typical $\mathbb{Z}_{2}$ reduction: $K U^{\dagger}\left(\lambda^{*}\right) K^{-1}=U(\lambda)$ where $K=\operatorname{diag}\left(\epsilon_{1}, \epsilon_{2}, 1, \epsilon_{2}, \epsilon_{1}\right)$
with $\epsilon_{k}= \pm 1$.

$$
J_{k}=J_{k}^{*}, \quad Q_{\overline{10}}=-\epsilon_{1} \epsilon_{2} Q_{10}^{*}, \quad Q_{\overline{01}}=-\epsilon_{2} Q_{01}^{*}, \quad Q_{\overline{11}}=-\epsilon_{1} Q_{11}^{*}, \quad Q_{\overline{12}}=-\epsilon_{1} \epsilon_{2} Q_{12}^{*}
$$

Reduced NLEE is given by 4 equation

$$
\begin{aligned}
i\left(J_{1}-J_{2}\right) Q_{10, t}(x, t)-i\left(I_{1}-I_{2}\right) Q_{10, x}(x, t)-k \epsilon_{2} Q_{11}(x, t) Q_{01}^{*}(x, t) & =0 \\
i J_{1} Q_{11, t}(x, t)-i I_{1} Q_{11, x}(x, t)-k\left(Q_{10} Q_{01}+\epsilon_{2} Q_{12} Q_{01}^{*}\right)(x, t) & =0 \\
i\left(J_{1}+J_{2}\right) Q_{12, t}(x, t)-i\left(I_{1}+I_{2}\right) Q_{12, x}(x, t)-k Q_{11}(x, t) Q_{01}(x, t) & =0 \\
i J_{2} Q_{01, t}(x, t)-i I_{2} Q_{01, x}(x, t)-k \epsilon_{1}\left(Q_{11}^{*} Q_{12}+\epsilon_{2} Q_{10}^{*} Q_{11}\right)(x, t) & =0 .
\end{aligned}
$$

Then $\lambda^{ \pm}=\mu \pm i \nu$, and $|m\rangle=K|n\rangle^{*}$ and 1-soliton solution becomes

$$
\begin{aligned}
Q_{10}(z) & =\frac{-2 i \nu}{\left\langle n^{*}\right| K|n\rangle}\left(\epsilon_{2} e^{-i\left(\lambda^{+} z_{1}-\left(\lambda^{+}\right)^{*} z_{2}\right)} n_{0,1} n_{0,2}^{*}+\epsilon_{1} e^{i\left(\lambda^{+} z_{2}-\left(\lambda^{+}\right)^{*} z_{1}\right)} n_{0,4} n_{0,5}^{*}\right) \\
Q_{11}(z) & =\frac{-2 i \nu}{\left\langle n^{*}\right| K|n\rangle}\left(e^{-i \lambda^{+} z_{1}} n_{0,1} n_{0,3}^{*}-\epsilon_{1} e^{-i\left(\lambda^{+}\right)^{*} z_{1}} n_{0,3} n_{0,5}^{*}\right) \\
Q_{12}(z) & =\frac{-2 i \nu}{\left\langle n^{*}\right| K|n\rangle}\left(\epsilon_{2} e^{-i\left(\lambda^{+} z_{1}+\left(\lambda^{+}\right)^{*} z_{2}\right)} n_{0,1} n_{0,4}^{*}+\epsilon_{1} e^{-i\left(\left(\lambda^{+}\right)^{*} z_{1}+\lambda^{+} z_{2}\right)} n_{0,2} n_{0,5}^{*}\right) \\
Q_{01}(z) & =\frac{-2 i \nu}{\left\langle n^{*}\right| K|n\rangle}\left(e^{-i \lambda^{+} z_{2}} n_{0,2} n_{0,3}^{*}+\epsilon_{2} e^{-i\left(\lambda^{+}\right)^{*} z_{2}} n_{0,3} n_{0,4}^{*}\right) \\
\left\langle n^{*}\right| K|n\rangle & =\epsilon_{1}\left|n_{0,1}\right|^{2} e^{2 \nu z_{1}}+\epsilon_{2}\left|n_{0,2}\right|^{2} e^{2 \nu z_{2}}+\left|n_{0,3}\right|^{2}+\epsilon_{2}\left|n_{0,4}\right|^{2} e^{-2 \nu z_{2}}+\epsilon_{1}\left|n_{0,5}\right|^{2} e^{-2 \nu z_{1}},
\end{aligned}
$$

Solitons associated with subalgebras of so(5):

1. Suppose $n_{0,1}=n_{0,5}=0$. The only nonzero waves are $Q_{01}, Q_{\overline{01}}$ related to the simple root $\alpha_{2}-$ a $s o(3)$ soliton.
2. Another $s l(2)$ soliton is derived when $n_{0,2}=n_{0,4}=0$. Then $Q_{11}, Q_{\overline{11}}$ are nonvanishing; the so(3) subalgebra is connected with the root $e_{1}=\alpha_{1}+\alpha_{2}$.
3. Let $n_{0,3}=0$. Then $Q_{10}, Q_{\overline{10}}$ and $Q_{12}, Q_{\overline{12}}$ are nonzero waves. The corresponding subalgebra is $s o(3) \oplus s o(3) \approx s o(4)$.
4. If $n_{0,1}^{*}=n_{0,5}, n_{0,2}^{*}=n_{0,4}$ and $n_{0,3}^{*}=n_{0,3}$ then

$$
\begin{aligned}
Q_{10}(z) & =\frac{-i \nu}{\Delta_{1}} \sinh 2 \theta_{0} \cosh \nu\left(z_{1}+z_{2}\right) e^{-i \mu\left(z_{1}-z_{2}-\delta_{1}+\delta_{2}\right)} \\
Q_{11}(z) & =-\frac{2 \sqrt{2} i \nu}{\Delta_{1}} \sinh \theta_{0} \sinh \nu z_{1} e^{-i \mu\left(z_{1}-\delta_{1}\right)} \\
Q_{12}(z) & =\frac{-i \nu}{\Delta_{1}} \sinh 2 \theta_{0} \cosh \nu\left(z_{1}-z_{2}\right) e^{-i \mu\left(z_{1}+z_{2}-\delta_{1}-\delta_{2}\right)} \\
Q_{01}(z) & =\frac{-2 \sqrt{2} i \nu}{\Delta_{1}} \cosh \theta_{0} \cosh \nu z_{2} e^{-i \mu\left(z_{2}-\delta_{2}\right)} \\
n_{0,1} & =\frac{n_{0,3}}{\sqrt{2}} \sinh \theta_{0} e^{i \mu \delta_{1}}, \quad n_{0,2}=\frac{n_{0,3}}{\sqrt{2}} \cosh \theta_{0} e^{i \mu \delta_{2}}, \quad \theta_{0} \in \mathbb{R} \\
\Delta_{1}(x, t) & =2\left(\sinh ^{2} \theta_{0} \sinh ^{2}\left(\nu z_{1}\right)+\cosh ^{2} \theta_{0} \cosh ^{2}\left(\nu z_{2}\right)\right)
\end{aligned}
$$

If $\theta_{0}=0$ then a single wave remains nontrivial:

$$
Q_{01}(x, t)=\frac{-\sqrt{2} i \nu}{\cosh \nu z_{2}} e^{-i \mu\left(z_{2}-\delta_{2}\right)}
$$

## $6.2 \mathbb{Z}_{2} \times \mathbb{Z}_{2}$ reductions and Doublet Solitons

An additional $\mathbb{Z}_{2}$ symmetry:

$$
\begin{aligned}
\chi^{-}(x, \lambda) & =K_{1}\left(\left(\chi^{+}\right)^{\dagger}\left(x, \lambda^{*}\right)\right)^{-1} K_{1}^{-1} \\
\chi^{-}(x, \lambda) & =K_{2}\left(\left(\chi^{+}\right)^{T}(x,-\lambda)\right)^{-1} K_{2}^{-1}
\end{aligned}
$$

where $K_{1,2} \in S O(5)$ and $\left[K_{1}, K_{2}\right]=0$. Also $U(x, \lambda)$ satisfies both symmetry conditions. The $\mathbb{Z}_{2} \times \mathbb{Z}_{2}$-reduced 4 -wave system reads

$$
\begin{aligned}
\left(J_{1}-J_{2}\right) \mathbf{q}_{10, t}(x, t)-\left(I_{1}-I_{2}\right) \mathbf{q}_{10, x}(x, t)+k \mathbf{q}_{11}(x, t) \mathbf{q}_{01}(x, t) & =0 \\
J_{1} \mathbf{q}_{11, t}(x, t)-I_{1} \mathbf{q}_{11, x}(x, t)+k\left(\mathbf{q}_{12}(x, t)-\mathbf{q}_{10}(x, t)\right) \mathbf{q}_{01}(x, t) & =0 \\
\left(J_{1}+J_{2}\right) \mathbf{q}_{12, t}(x, t)-\left(I_{1}+I_{2}\right) \mathbf{q}_{12, x}(x, t)-k \mathbf{q}_{11}(x, t) \mathbf{q}_{01}(x, t) & =0 \\
J_{2} \mathbf{q}_{01, t}(x, t)-I_{2} \mathbf{q}_{01, x}(x, t)+k\left(\mathbf{q}_{10}(x, t)+\mathbf{q}_{12}(x, t)\right) q_{11}(x, t) & =0
\end{aligned}
$$

where $\mathbf{q}_{10}(x, t), \mathbf{q}_{11}(x, t), \mathbf{q}_{12}(x, t)$ and $\mathbf{q}_{01}(x, t)$ are real valued fields.
The dressing factor $u(x, \lambda)$ must be invariant under the action of $\mathbb{Z}_{2} \times \mathbb{Z}_{2}$, i.e.

$$
\begin{gather*}
K_{1}\left(u^{\dagger}\left(x, \lambda^{*}\right)\right)^{-1} K_{1}^{-1}=u(x, \lambda)  \tag{39}\\
K_{2}\left(u^{T}(x,-\lambda)\right)^{-1} K_{2}^{-1}=u(x, \lambda) \tag{40}
\end{gather*}
$$

If $K_{1}=K_{2}=\mathbb{1}$ one way to satisfy both conditions is to choose the poles of $u(x, \lambda)$ at $\lambda^{ \pm}= \pm i \nu$ and $|m(x, t)\rangle=|n(x, t)\rangle=e^{\nu(J x+I t)}\left|n_{0}\right\rangle$ real.

The doublet solution becomes

$$
\begin{aligned}
\mathbf{q}_{10}(x, t) & =-\frac{4 \nu}{\langle n \mid n\rangle} N_{1} N_{2} \cosh \nu\left[\left(J_{1}+J_{2}\right) x+\left(I_{1}+I_{2}\right) t-\xi_{1}-\xi_{2}\right] \\
\mathbf{q}_{11}(x, t) & =-\frac{4 \nu}{\langle n \mid n\rangle} N_{1} n_{0,3} \sinh \nu\left(J_{1} x+I_{1} t-\xi_{1}\right) \\
\mathbf{q}_{12}(x, t) & =-\frac{4 \nu}{\langle n \mid n\rangle} N_{1} N_{2} \cosh \nu\left[\left(J_{1}-J_{2}\right) x+\left(I_{1}-I_{2}\right) t-\xi_{1}+\xi_{2}\right] \\
\mathbf{q}_{01}(x, t) & =-\frac{4 \nu}{\langle n \mid n\rangle} N_{2} n_{0,3} \cosh \nu\left(J_{2} x+I_{2} t-\xi_{2}\right) \\
\langle n(x, t) \mid n(x, t)\rangle & =2 N_{1}^{2} \cosh 2 \nu\left(J_{1} x+I_{1} t-\xi_{1}\right)+2 N_{2}^{2} \cosh 2 \nu\left(J_{2} x+I_{2} t-\xi_{2}\right)+n_{0,3}^{2}
\end{aligned}
$$

where

$$
\xi_{1}:=\frac{1}{2 \nu} \ln \frac{n_{0,5}}{n_{0,1}}, \quad \xi_{2}:=\frac{1}{2 \nu} \ln \frac{n_{0,4}}{n_{0,2}}, \quad N_{1}=\sqrt{n_{0,1} n_{0,5}}, \quad N_{2}=\sqrt{n_{0,2} n_{0,4}}
$$

## $6.3 \mathbb{Z}_{2} \times \mathbb{Z}_{2}$ reductions and Quadruplet Solitons

Now the $\mathbb{Z}_{2} \times \mathbb{Z}_{2}$-invariance of $u(x, t, \lambda)$ is ensured by adding two more terms:

$$
\begin{aligned}
u(x, t, \lambda) & =\mathbb{1}+\frac{A(x, t)}{\lambda-\lambda^{+}}+\frac{K_{1} S A^{*}(x, t)\left(K_{1} S\right)^{-1}}{\lambda-\left(\lambda^{+}\right)^{*}}-\frac{K_{2} S A(x, t)\left(K_{2} S\right)^{-1}}{\lambda+\lambda^{+}} \\
& -\frac{K_{1} K_{2} A^{*}(x, t)\left(K_{1} K_{2}\right)^{-1}}{\lambda+\left(\lambda^{+}\right)^{*}}
\end{aligned}
$$

where $A(x, t)=|X(x, t)\rangle\langle F(x, t)|$ and

$$
|F(x, t)\rangle=e^{i \lambda^{+}(J x+I t)}\left|F_{0}\right\rangle
$$

For $|X(x, t)\rangle$ we get a linear system of equations. Skipping the details we obtain the generic quadruplet solution to the 4 -wave system associated with the $\mathbf{B}_{2}$ algebra
$\mathbf{q}_{10}=\frac{4}{\Delta} \operatorname{Im}\left[a^{*} N_{1} \cosh \left(\varphi_{1}+\varphi_{2}\right)-\frac{i m N_{1}^{*}}{\mu \nu}\left(\mu \cosh \left(\varphi_{1}^{*}+\varphi_{2}\right)-i \nu \cosh \left(\varphi_{1}^{*}-\varphi_{2}\right)\right)\right] N_{2}$

$$
\begin{aligned}
& \mathbf{q}_{11}=\frac{4}{\Delta} \operatorname{Im}\left[a^{*} N_{1} \sinh \left(\varphi_{1}\right)-\frac{i m \lambda^{+}}{\mu \nu} N_{1}^{*} \sinh \left(\varphi_{1}^{*}\right)\right] m_{0}^{3} \\
& \mathbf{q}_{12}=\frac{4}{\Delta} \operatorname{Im}\left[a^{*} N_{1} \cosh \left(\varphi_{1}-\varphi_{2}\right)-\frac{i m N_{1}^{*}}{\mu \nu}\left(\mu \cosh \left(\varphi_{1}^{*}-\varphi_{2}\right)-i \nu \cosh \left(\varphi_{1}^{*}+\varphi_{2}\right)\right)\right] N_{2} \\
& \mathbf{q}_{01}=\frac{4}{\Delta} \operatorname{Im}\left[a^{*} N_{2} \cosh \left(\varphi_{2}\right)-\frac{i m \lambda^{+*}}{\mu \nu} N_{2}^{*} \cosh \left(\varphi_{2}^{*}\right)\right] m_{0}^{3} .
\end{aligned}
$$

where

$$
\begin{aligned}
& a(x, t)=\frac{1}{\mu+i \nu}\left[N_{1}^{2} \cosh 2 \varphi_{1}+N_{2}^{2} \cosh 2 \varphi_{2}+\frac{F_{0,3}^{2}}{2}\right], \quad b(x, t)=\frac{m(x, t)}{i \nu}, \\
& c(x, t)=\frac{m(x, t)}{\mu}, \quad m(x, t)=\left|N_{1}\right|^{2} \cosh \left(2 \operatorname{Re} \varphi_{1}\right)+\left|N_{2}\right|^{2} \cosh \left(2 \operatorname{Re} \varphi_{2}\right)+\frac{\left|m_{0}^{3}\right|^{2}}{2}, \\
& N_{\sigma}:=\sqrt{m_{0}^{\sigma} m_{0}^{6-\sigma}}, \quad \varphi_{\sigma}(x, t):=i \lambda^{+}\left(J_{\sigma} x+I_{\sigma} t\right)+\frac{1}{2} \log \frac{m_{0}^{\sigma}}{m_{0}^{6-\sigma}}, \quad \sigma=1,2 .
\end{aligned}
$$

Other inequivalent reductions: we can use automorphisms $\tilde{K}_{1}$ and/or
$\tilde{K}_{2}$ taking values in the Weyl group.

## 7 The Generalized Fourier Transforms for Non-regular $J$

We show that the ISM can be viewed as generalized Fourier transform (GFT). We determine explicitly the proper generalizations of the usual exponents. We also introduce a skew-scalar product on $\mathcal{M}$ which provides it with a symplectic structure.

### 7.1 The Wronskian relations

Along with the Lax operator we consider associated systems:

$$
\begin{align*}
& i \frac{d \hat{\psi}}{d x}-\hat{\psi}(x, t, \lambda) U(x, t, \lambda)=0, \quad U(x, \lambda)=Q(x)-\lambda J  \tag{41}\\
& i \frac{d \delta \psi}{d x}+\delta U(x, t, \lambda) \psi(x, t, \lambda)+U(x, t, \lambda) \delta \psi(x, t, \lambda)=0  \tag{42}\\
& i \frac{d \dot{\psi}}{d x}-\lambda J \psi(x, t, \lambda)+U(x, t, \lambda) \dot{\psi}(x, t, \lambda)=0 \tag{43}
\end{align*}
$$

where $\delta \psi$ corresponds to a given variation $\delta Q(x, t)$ of the potential, while by dot we denote the derivative with respect to the spectral parameter.

We start with the identity:

$$
\begin{equation*}
\left.(\hat{\chi} J \chi(x, \lambda)-J)\right|_{x=-\infty} ^{\infty}=i \int_{-\infty}^{\infty} d x \hat{\chi}[J, Q(x)] \chi(x, \lambda) \tag{44}
\end{equation*}
$$

where $\chi(x, \lambda)$ can be any fundamental solution of $L$.
One can use the asymptotics of $\chi^{ \pm}(x, \lambda)$ for $x \rightarrow \pm \infty$ to express the l.h.sides of the Wronskian relations in terms of the scattering data. Then

$$
\begin{align*}
& \left.\left\langle\left(\hat{\chi}^{ \pm} J \chi^{ \pm}(x, \lambda)-J\right) E_{\beta}\right\rangle\right|_{x=-\infty} ^{\infty}=i \int_{-\infty}^{\infty} d x\left\langle\left([J, Q(x)] e_{\beta}^{ \pm}(x, \lambda)\right)\right\rangle \\
& \left.\left\langle\left(\hat{\chi}^{\prime}, \pm J \chi^{\prime, \pm}(x, \lambda)-J\right) E_{\beta}\right\rangle\right|_{x=-\infty} ^{\infty}=i \int_{-\infty}^{\infty} d x\left\langle\left([J, Q(x)] e_{\beta}^{\prime, \pm}(x, \lambda)\right)\right\rangle \tag{45}
\end{align*}
$$

where

$$
\left.\begin{array}{rl}
e_{\beta}^{ \pm}(x, \lambda) & =\chi^{ \pm} E_{\beta} \hat{\chi}^{ \pm}(x, \lambda), \\
e_{\beta}^{\prime, \pm}(x, \lambda) & =\chi^{\prime, \pm} E_{\beta} \hat{\chi}^{\prime, \pm}(x, \lambda), \tag{46}
\end{array} \quad \boldsymbol{e}_{\beta}^{\prime, \pm}(x, \lambda)=P_{0 J}\left(\chi^{ \pm} E_{\beta} \hat{\chi}^{ \pm}(x, \lambda)\right), \chi^{\prime, \pm} E_{\beta} \hat{\chi}^{\prime, \pm}(x, \lambda)\right), ~ l
$$

are the natural generalization of the 'squared solutions' introduced first for the $s l(2)$-case. By $P_{0 J}$ we have denoted the projector $P_{0 J}=\operatorname{ad}_{J}^{-1} \mathrm{ad}{ }_{J}$ on the block-off-diagonal part of the corresponding matrix-valued function.

The right hand sides of eq. (46) can be written down with the skewscalar product:

$$
\begin{equation*}
\llbracket[X, Y]]=\int_{-\infty}^{\infty} d x\langle X(x),[J, Y(x)]\rangle \tag{47}
\end{equation*}
$$

where $\langle X, Y\rangle$ is the Killing form; in what follows we assume that the Cartan-Weyl generators satisfy $\left\langle E_{\alpha}, E_{-\beta}\right\rangle=\delta_{\alpha, \beta}$ and $\left\langle H_{j}, H_{k}\right\rangle=\delta_{j k}$. The product is skew-symmetric $[[X, Y]]=-[[Y, X]$ and is non-degenerate
on the space of allowed potentials $\mathcal{M}$. Thus we find

$$
\begin{align*}
& \rho_{\beta}^{+}=-i\left[\left[Q(x), \boldsymbol{e}_{\beta}^{\prime,+}\right]\right], \quad \rho_{\beta}^{-}=-i\left[\left[Q(x), \boldsymbol{e}_{-\beta}^{\prime,-}\right]\right. \\
& \tau_{\beta}^{+}=-i\left[\left[Q(x), \boldsymbol{e}_{-\beta}^{+}\right]\right], \quad \tau_{\beta}^{-}=-i\left[\left[Q(x), \boldsymbol{e}_{\beta}^{-}\right]\right]  \tag{48}\\
& \vec{\rho}^{+}=\frac{\vec{b}^{+}}{m_{1}^{+}}, \quad \vec{\rho}=\frac{\vec{B}^{-}}{m_{1}^{-}}, \quad \vec{\tau}^{+}=\frac{\vec{b}^{-}}{m_{1}^{+}}, \quad \vec{\tau}^{-}=\frac{\vec{B}^{+}}{m_{1}^{-}}
\end{align*}
$$

Thus the mappings $\mathfrak{F}: Q(x, t) \rightarrow \mathfrak{T}_{i}$ can be viewed as generalized Fourier transform in which $\boldsymbol{e}_{\beta}^{ \pm}(x, \lambda)$ and $\boldsymbol{e}_{\beta}^{\prime, \pm}(x, \lambda)$ can be viewed as generalizations of the standard exponentials.

We apply ideas similar to the ones above and get:

$$
\begin{align*}
& \left.\delta \rho_{\beta}^{+}=-i\left[\operatorname{ad}_{J}^{-1} \delta Q(x), \boldsymbol{e}_{\beta}^{\prime,+}\right]\right], \quad \delta \rho_{\beta}^{-}=i\left[\left[\operatorname{ad}_{J}^{-1} \delta Q(x), \boldsymbol{e}_{-\beta}^{\prime,-}\right]\right], \\
& \left.\delta \tau_{\beta}^{+}=i\left[\operatorname{ad}_{J}^{-1} \delta Q(x), \boldsymbol{e}_{-\beta}^{+}\right]\right], \quad \delta \tau_{\beta}^{-}=-i\left[\left[\operatorname{ad}_{J}^{-1} \delta Q(x), \boldsymbol{e}_{\beta}^{-}\right]\right] \tag{49}
\end{align*}
$$

where $\beta \in \Delta_{1}^{+}$.
These relations are basic in the analysis of the related NLEE and their Hamiltonian structures. Assume that

$$
\begin{equation*}
\delta Q(x, t)=Q_{t} \delta t+\mathcal{O}\left((\delta t)^{2}\right) \tag{50}
\end{equation*}
$$

Keeping only the first order terms with respect to $\delta t$ we find:

$$
\begin{array}{rlrl}
\frac{d \rho_{\beta}^{+}}{d t} & \left.=-i\left[\operatorname{ad}_{J}^{-1} Q_{t}(x), \boldsymbol{e}_{\beta}^{\prime,+}\right]\right], & \frac{d \rho_{\beta}^{-}}{d t} & =i\left[\left[\operatorname{ad}_{J}^{-1} Q_{t}(x), \boldsymbol{e}_{-\beta}^{\prime,-}\right]\right.  \tag{51}\\
\frac{d \tau_{\beta}^{+}}{d t} & \left.=i\left[\operatorname{ad}_{J}^{-1} Q_{t}(x), \boldsymbol{e}_{-\beta}^{+}\right]\right], & \left.\frac{d \tau_{\beta}^{-}}{d t}=-i\left[\operatorname{ad}_{J}^{-1} Q_{t}(x), \boldsymbol{e}_{\beta}^{-}\right]\right],
\end{array}
$$

### 7.2 Completeness of the 'squared solutions'

Let us introduce the sets of 'squared solutions'

$$
\begin{align*}
& \{\boldsymbol{\Psi}\}=\{\boldsymbol{\Psi}\}_{\mathrm{c}} \cup\{\boldsymbol{\Psi}\}_{\mathrm{d}}, \quad\{\boldsymbol{\Phi}\}=\{\boldsymbol{\Phi}\}_{\mathrm{c}} \cup\{\boldsymbol{\Phi}\}_{\mathrm{d}}, \\
& \{\boldsymbol{\Psi}\}_{\mathrm{c}} \equiv\left\{\boldsymbol{e}_{-\alpha}^{+}(x, \lambda), \quad \boldsymbol{e}_{\alpha}^{-}(x, \lambda), \quad \lambda \in \mathbb{R}, \quad \alpha \in \Delta_{1}^{+}\right\}, \\
& \{\boldsymbol{\Psi}\}_{\mathrm{d}} \equiv\left\{\boldsymbol{e}_{\mp \alpha ; j}^{ \pm}(x), \quad \dot{\boldsymbol{e}}_{\mp \alpha ; j}^{ \pm}(x), \quad \ddot{\boldsymbol{e}}_{\mp \alpha ; j}^{ \pm}(x), \quad \dddot{\boldsymbol{e}}_{\mp \alpha ; j}^{ \pm}(x), \quad \alpha \in \Delta_{1}^{+},\right\},  \tag{53}\\
& \{\boldsymbol{\Phi}\}_{\mathrm{c}} \equiv\left\{\boldsymbol{e}_{\alpha}^{+}(x, \lambda), \quad \boldsymbol{e}_{-\alpha}^{-}(x, \lambda), \quad \lambda \in \mathbb{R}, \quad \alpha \in \Delta_{1}^{+}\right\}, \\
& \{\boldsymbol{\Phi}\}_{\mathrm{d}} \equiv\left\{\boldsymbol{e}_{ \pm \alpha ; j}^{ \pm}(x), \quad \dot{\boldsymbol{e}}_{ \pm \alpha ; j}^{ \pm}(x), \quad \ddot{\boldsymbol{e}}_{ \pm \alpha ; j}^{ \pm}(x), \quad \dddot{\boldsymbol{e}}_{ \pm \alpha ; j}^{ \pm}(x), \quad \alpha \in \Delta_{1}^{+},\right\}, \tag{54}
\end{align*}
$$

where $j=1, \ldots, N$ and the subscripts 'c' and ' d ' refer to the continuous and discrete spectrum of $L$, the latter consisting of $2 N$ discrete eigenvalues $\lambda_{j}^{ \pm} \in \mathbb{C}_{ \pm}$.
Theorem 1 (see V.S.G. (1998)). The sets $\{\boldsymbol{\Psi}\}$ and $\{\boldsymbol{\Phi}\}$ form complete sets of functions in $\mathcal{M}_{J}$. The completeness relation has the form:

$$
\begin{gather*}
\delta(x-y) \Pi_{0 J}=\frac{1}{\pi} \int_{-\infty}^{\infty} d \lambda\left(G_{1}^{+}(x, y, \lambda)-G_{1}^{-}(x, y, \lambda)\right) \\
-2 i \sum_{j=1}^{N}\left(G_{1, j}^{+}(x, y)+G_{1, j}^{-}(x, y)\right),  \tag{55}\\
\Pi_{0 J}=\sum_{\alpha \in \Delta_{1}^{+}}\left(E_{\alpha} \otimes E_{-\alpha}-E_{-\alpha} \otimes E_{\alpha}\right),  \tag{56}\\
G_{1}^{ \pm}(x, y, \lambda)=\sum_{\alpha \in \Delta_{1}^{+}} e_{ \pm \alpha}^{ \pm}(x, \lambda) \otimes \boldsymbol{e}_{\mp \alpha}^{+}(y, \lambda), \\
G_{1, j}^{ \pm}(x, y)=\sum_{\alpha \in \Delta_{1}^{+}}\left(\dot{e}_{ \pm \alpha ; j}^{ \pm}(x) \otimes \boldsymbol{e}_{\mp \alpha ; j}^{ \pm}(y)+\boldsymbol{e}_{ \pm \alpha ; j}^{ \pm}(x) \otimes \dot{\boldsymbol{e}}_{\mp \alpha ; j}^{ \pm}(y) .\right. \tag{57}
\end{gather*}
$$

Idea of the proof. Apply the contour integration method to the function

$$
\begin{align*}
G^{ \pm}(x, y, \lambda) & =G_{1}^{ \pm}(x, y, \lambda) \theta(y-x)-G_{2}^{ \pm}(x, y, \lambda) \theta(x-y) \\
G_{1}^{ \pm}(x, y, \lambda) & =\sum_{\alpha \in \Delta_{1}^{+}} \boldsymbol{e}_{ \pm \alpha}^{ \pm}(x, \lambda) \otimes \boldsymbol{e}_{\mp \alpha}^{ \pm}(y, \lambda), \\
G_{2}^{ \pm}(x, y, \lambda) & =\sum_{\alpha \in \Delta_{0} \cup \Delta_{1}^{-}} \boldsymbol{e}_{ \pm \alpha}^{-}(x, \lambda) \otimes \boldsymbol{e}_{\mp \alpha}^{-}(y, \lambda)+\sum_{j=1}^{r} \boldsymbol{h}_{j}^{ \pm}(x, \lambda) \otimes \boldsymbol{h}_{j}^{ \pm}(y, \lambda), \\
\boldsymbol{h}_{j}^{ \pm}(x, \lambda) & =\chi^{ \pm}(x, \lambda) H_{j} \hat{\chi}^{ \pm}(x, \lambda), \tag{58}
\end{align*}
$$

and calculate the integral

$$
\begin{equation*}
\mathcal{J}_{G}(x, y)=\frac{1}{2 \pi i} \oint_{\gamma_{+}} d \lambda G^{+}(x, y, \lambda)-\frac{1}{2 \pi i} \oint_{\gamma_{-}} d \lambda G^{-}(x, y, \lambda) \tag{59}
\end{equation*}
$$

in two ways: i) via the Cauchy residue theorem and ii) integrating along the contours.


Фигура 1: The contours $\gamma_{ \pm}=\mathbb{R} \cup \gamma_{ \pm \infty}$.

Remark 1. There is a dual completeness relation for the 'squared solutions' obtained by replacing all $e_{\alpha}^{ \pm}(x, \lambda)$ with $e_{\alpha}^{\prime, \pm}(x, \lambda)$.

### 7.3 Expansions over the ,squared" solutions

Using the completeness relations one can expand any generic element $F(x)$ of the phase space $\mathcal{M}$ over each of the sets of 'squared solutions':

$$
\begin{align*}
F(x) & =\frac{1}{\pi} \int_{-\infty}^{\infty} d \lambda \sum_{\alpha \in \Delta_{1}^{+}}\left(e_{\alpha}^{+}(x, \lambda) \gamma_{F ;-\alpha}^{+}(\lambda)-e_{-\alpha}^{-}(x, \lambda) \gamma_{F ; \alpha}^{-}(\lambda)\right) \\
& -2 i \sum_{j=1}^{N} \sum_{\alpha \in \Delta_{1}^{+}}\left(Z_{F ; \alpha, j}^{+}(x)+Z_{F ; \alpha, j}^{-}(x)\right), \tag{60}
\end{align*}
$$

$$
\begin{align*}
F(x) & =-\frac{1}{\pi} \int_{-\infty}^{\infty} d \lambda \sum_{\alpha \in \Delta_{1}^{+}}\left(\boldsymbol{e}_{-\alpha}^{+}(x, \lambda) \tilde{\gamma}_{F ; \alpha}^{+}(\lambda)-\boldsymbol{e}_{\alpha}^{-}(x, \lambda) \tilde{\gamma}_{F ;-\alpha}^{-}(\lambda)\right) \\
& +2 i \sum_{j=1}^{N} \sum_{\alpha \in \Delta_{1}^{+}}\left(\tilde{Z}_{F ; \alpha, j}^{+}(x)+\tilde{Z}_{F ; \alpha, j}^{-}(x)\right) \tag{61}
\end{align*}
$$

where

$$
\begin{gather*}
\gamma_{F ; \alpha}^{ \pm}(\lambda)=\left[\left[\boldsymbol{e}_{ \pm \alpha}^{ \pm}(y, \lambda), F(y)\right], \quad \tilde{\gamma}_{F ; \alpha}^{ \pm}(\lambda)=\left[\left[\boldsymbol{e}_{\mp \alpha}^{ \pm}(y, \lambda), F(y)\right]\right],\right. \\
Z_{F ; j}^{ \pm}(x)=\operatorname{Res}_{\lambda=\lambda_{j}^{ \pm}} \boldsymbol{e}_{\mp \alpha}^{ \pm}(x, \lambda) \gamma_{F ; \mp \alpha}^{ \pm}(\lambda), \quad \tilde{Z}_{F ; j}^{ \pm}(x)=\operatorname{Res}_{\lambda=\lambda_{j}^{+}} \boldsymbol{e}_{ \pm \alpha}^{ \pm}(x, \lambda) \gamma_{F ; \pm \alpha}^{+}(\lambda) \tag{63}
\end{gather*}
$$

Proposition 1. The function $F(x) \equiv 0$ if and only if all its expansion coefficients vanish, i.e.:

$$
\begin{array}{lll}
\gamma_{F ;-\alpha}^{+}(\lambda)=\gamma_{F ; \alpha}^{-}(\lambda)=0, & \alpha \in \Delta_{1}^{+} ; & Z_{F ; \alpha, j}^{+}(x)=Z_{F ; \alpha, j}^{-}(x)=0 \\
\tilde{\gamma}_{F ; \alpha}^{+}(\lambda)=\tilde{\gamma}_{F ;-\alpha}^{-}(\lambda)=0, & \alpha \in \Delta_{1}^{+} ; & \tilde{Z}_{F ; \alpha, j}^{+}(x)=\tilde{Z}_{F ; \alpha, j}^{-}(x)=0 ; \\
\text { where } j=1, \ldots, N .
\end{array}
$$

7.4 Expansions of $Q(x)$ and $\operatorname{ad}_{J}^{-1} \delta Q(x)$.

$$
\begin{align*}
Q(x) & =-\frac{i}{\pi} \int_{-\infty}^{\infty} d \lambda \sum_{\alpha \in \Delta_{1}^{+}}\left(\tau_{\alpha}^{+}(\lambda) e_{\alpha}^{+}(x, \lambda)-\tau_{\alpha}^{-}(\lambda) e_{-\alpha}^{-}(x, \lambda)\right) \\
& -2 \sum_{j=1}^{N} \sum_{\alpha \in \Delta_{1}^{+}}\left(\underset{\lambda=\lambda_{j}^{+}}{\operatorname{Res}} \tau_{\alpha}^{+} e_{\alpha}^{+}(x, \lambda)+\underset{\lambda=\lambda_{j}^{-}}{\operatorname{Res}} \tau_{\alpha}^{-} e_{-\alpha}^{-}(x, \lambda)\right),  \tag{64}\\
Q(x) & =\frac{i}{\pi} \int_{-\infty}^{\infty} d \lambda \sum_{\alpha \in \Delta_{1}^{+}}\left(\rho_{\alpha}^{+}(\lambda) \boldsymbol{e}_{-\alpha}^{\prime+}(x, \lambda)-\rho_{\alpha}^{-}(\lambda) \boldsymbol{e}_{\alpha}^{\prime,-}(x, \lambda)\right) \\
& +2 \sum_{j=1}^{N} \sum_{\alpha \in \Delta_{1}^{+}}\left(\operatorname{Res}_{\lambda=\lambda_{j}^{+}} \rho_{\alpha}^{+} e_{\alpha}^{\prime,+}(x, \lambda)+\underset{\lambda=\lambda_{j}^{-}}{\operatorname{Res}} \rho_{\alpha}^{-} \boldsymbol{e}_{\alpha}^{\prime,-}(x, \lambda)\right), \tag{65}
\end{align*}
$$

$$
\begin{align*}
\operatorname{ad}_{J}^{-1} \delta Q(x) & =\frac{i}{\pi} \int_{-\infty}^{\infty} d \lambda \sum_{\alpha \in \Delta_{1}^{+}}\left(\delta \tau_{\alpha}^{+}(\lambda) \boldsymbol{e}_{\alpha}^{+}(x, \lambda)+\delta \tau_{\alpha}^{-}(\lambda) \boldsymbol{e}_{-\alpha}^{-}(x, \lambda)\right) \\
& +2 \sum_{j=1}^{N} \sum_{\alpha \in \Delta_{1}^{+}}\left(\operatorname{Res}_{\lambda=\lambda_{j}^{+}} \delta \tau_{\alpha}^{+} \boldsymbol{e}_{\alpha}^{+}(x, \lambda)-\operatorname{Res}_{\lambda=\lambda_{j}^{-}} \delta \tau_{\alpha}^{-} \boldsymbol{e}_{-\alpha}^{-}(x, \lambda)\right)  \tag{66}\\
\operatorname{ad}_{J}^{-1} \delta Q(x) & =\frac{i}{\pi} \int_{-\infty}^{\infty} d \lambda \sum_{\alpha \in \Delta_{1}^{+}}\left(\delta \rho_{\alpha}^{+}(\lambda) \boldsymbol{e}_{-\alpha}^{\prime,+}(x, \lambda)+\delta \rho_{\alpha}^{-}(\lambda) \boldsymbol{e}_{\alpha}^{\prime,-}(x, \lambda)\right) \\
& -2 \sum_{j=1}^{N} \sum_{\alpha \in \Delta_{1}^{+}}\left(\operatorname{Res}_{\lambda=\lambda_{j}^{+}} \delta \rho_{\alpha}^{+} \boldsymbol{e}_{-\alpha}^{\prime,+}(x, \lambda)-\operatorname{Res}_{\lambda=\lambda_{j}^{-}} \delta \rho_{\alpha}^{-} \boldsymbol{e}_{\alpha}^{\prime,-}(x, \lambda)\right) \tag{67}
\end{align*}
$$

These expansions combined with the proposition above give another way to establish the one-to-one correspondence between $Q(x)$ and each of the minimal sets of scattering data $\mathcal{T}_{1}$ and $\mathcal{T}_{2}$.

$$
\begin{align*}
\operatorname{ad}_{J}^{-1} \frac{d Q}{d t} & =\frac{i}{\pi} \int_{-\infty}^{\infty} d \lambda \sum_{\alpha \in \Delta_{1}^{+}}\left(\frac{d \tau_{\alpha}^{+}}{d t} e_{\alpha}^{+}(x, \lambda)+\frac{d \tau_{\alpha}^{-}}{d t} e_{-\alpha}^{-}(x, \lambda)\right) \\
& +2 \sum_{j=1}^{N} \sum_{\alpha \in \Delta_{1}^{+}}\left(\operatorname{Res}_{\lambda=\lambda_{j}^{+}} \frac{d \tau_{\alpha}^{+}}{d t} e_{\alpha}^{+}(x, \lambda)-\operatorname{Res}_{\lambda=\lambda_{j}^{-}} \frac{d \tau_{\alpha}^{-}}{d t} e_{-\alpha}^{-}(x, \lambda)\right) \tag{68}
\end{align*}
$$

$$
\begin{align*}
\operatorname{ad}_{J}^{-1} \frac{d Q}{d t} & =\frac{i}{\pi} \int_{-\infty}^{\infty} d \lambda \sum_{\alpha \in \Delta_{1}^{+}}\left(\frac{d \rho_{\alpha}^{+}}{d t} \boldsymbol{e}_{-\alpha}^{\prime,+}(x, \lambda)+\frac{d \rho_{\alpha}^{-}}{d t} \boldsymbol{e}_{\alpha}^{\prime,-}(x, \lambda)\right) \\
& -2 \sum_{j=1}^{N} \sum_{\alpha \in \Delta_{1}^{+}}\left(\operatorname{Res}_{\lambda=\lambda_{j}^{+}} \frac{d \rho_{\alpha}^{+}}{d t} \boldsymbol{e}_{-\alpha}^{\prime,+}(x, \lambda)-\operatorname{Res}_{\lambda=\lambda_{j}^{-}} \frac{d \rho_{\alpha}^{-}}{d t} \boldsymbol{e}_{\alpha}^{\prime,-}(x, \lambda)\right) \tag{69}
\end{align*}
$$

### 7.5 The generating operators

Introduce the generating operators $\Lambda_{ \pm}$through:

$$
\begin{array}{ll}
\left(\Lambda_{+}-\lambda\right) \boldsymbol{e}_{-\alpha}^{+}(x, \lambda)=0, & \left(\Lambda_{+}-\lambda\right) \boldsymbol{e}_{\alpha}^{-}(x, \lambda)=0 \\
\left(\Lambda_{-}-\lambda\right) \boldsymbol{e}_{\alpha}^{+}(x, \lambda)=0, & \left(\Lambda_{-}-\lambda\right) \boldsymbol{e}_{-\alpha}^{-}(x, \lambda)=0 \tag{70}
\end{array}
$$

Their derivation starts by introducing the splitting:

$$
\begin{equation*}
e_{\alpha}^{ \pm}(x, \lambda)=e_{\alpha}^{\mathrm{d}, \pm}(x, \lambda)+\boldsymbol{e}_{\alpha}^{ \pm}(x, \lambda), \quad e_{\alpha}^{\mathrm{d}, \pm}(x, \lambda)=\left(\mathbb{1}-P_{0 J}\right) e_{\alpha}^{ \pm}(x, \lambda), \tag{71}
\end{equation*}
$$

into the equation

$$
\begin{equation*}
i \frac{d e_{\alpha}}{d x}+\left[Q(x)-\lambda J, e_{\alpha}(x, \lambda)\right]=0 \tag{72}
\end{equation*}
$$

which is obviously satisfied by the 'squared solutions'. Then eq. (72) splits into:

$$
\begin{equation*}
i \frac{d e_{\alpha}^{\mathrm{d}, \pm}}{d x}+\left[Q(x), e_{\alpha}^{ \pm}(x, \lambda)\right]=0 \tag{73}
\end{equation*}
$$

$$
\begin{equation*}
i \frac{d \boldsymbol{e}_{\alpha}^{ \pm}}{d x}+\left[Q(x), e_{\alpha}^{\mathrm{d}, \pm}(x, \lambda)\right]=\lambda\left[J, \boldsymbol{e}_{\alpha}^{ \pm}(x, \lambda)\right] \tag{74}
\end{equation*}
$$

Eq. (73) can be integrated formally with the result

$$
\begin{array}{r}
e_{\alpha}^{\mathrm{d}, \pm}(x, \lambda)=C_{\alpha ; \epsilon}^{\mathrm{d}, \pm}(\lambda)+i \int_{\epsilon \infty}^{x} d y\left[Q(y), \boldsymbol{e}_{\alpha}^{ \pm}(y, \lambda)\right] \\
C_{\alpha ; \epsilon}^{\mathrm{d}, \pm}(\lambda)=\lim _{y \rightarrow \epsilon \infty} e_{\alpha}^{\mathrm{d}, \pm}(y, \lambda), \quad \epsilon= \pm 1 \tag{76}
\end{array}
$$

Next insert (75) into (74) and act on both sides by ad ${ }_{J}^{-1}$. This gives us:

$$
\begin{equation*}
\left(\Lambda_{ \pm}-\lambda\right) \boldsymbol{e}_{\alpha}^{ \pm}(x, \lambda)=i\left[C_{\alpha ; \epsilon}^{\mathrm{d}, \pm}(\lambda), \operatorname{ad}_{J}^{-1} Q(x)\right] \tag{77}
\end{equation*}
$$

where the generating operators $\Lambda_{ \pm}$are given by:

$$
\begin{gather*}
\Lambda_{ \pm} X(x) \equiv \operatorname{ad}_{J}^{-1}\left(i \frac{d X}{d x}+i\left[Q(x), \int_{ \pm \infty}^{x} d y[Q(y), X(y)]\right]\right) .  \tag{78}\\
\quad\left(\Lambda_{+}-\lambda\right) \boldsymbol{e}_{-\alpha}^{+}(x, \lambda)=0, \quad\left(\Lambda_{+}-\lambda\right) \boldsymbol{e}_{\alpha}^{-}(x, \lambda)=0 \tag{79}
\end{gather*}
$$

$$
\begin{equation*}
\left(\Lambda_{-}-\lambda\right) \boldsymbol{e}_{\alpha}^{+}(x, \lambda)=0, \quad\left(\Lambda_{-}-\lambda\right) \boldsymbol{e}_{-\alpha}^{-}(x, \lambda)=0 \tag{80}
\end{equation*}
$$

Thus the sets $\{\Psi\}$ and $\{\Phi\}$ are the complete sets of eigen- and adjoint functions of $\Lambda_{+}$and $\Lambda_{-}$.

## 8 Fundamental properties of the MNLS equations

### 8.1 The principal class of NLEE

By principle class of NLEE we mean the ones whose dispersion laws take the form:

$$
\begin{equation*}
F(\lambda)=f(\lambda) J \tag{81}
\end{equation*}
$$

where $f(\lambda)$ may be rational functions of $\lambda$ whose poles lie outside the spectrum of $L$. The corresponding NLEE is

$$
\begin{equation*}
i \operatorname{ad}_{J}^{-1} Q_{t}+f\left(\Lambda_{ \pm}\right) Q(x, t)=0 \tag{82}
\end{equation*}
$$

Theorem 2. The NLEE (82) are equivalent to: i) the equations (22) and ii) to the following evolution equations for the generalized Gauss
factors of $T(\lambda)$ :

$$
\begin{equation*}
i \frac{d S_{J}^{+}}{d t}+\left[F(\lambda), S_{J}^{+}\right]=0, \quad i \frac{d T_{J}^{-}}{d t}+\left[F(\lambda), T_{J}^{-}\right]=0 \tag{83}
\end{equation*}
$$

and

$$
\begin{equation*}
i \frac{d S_{J}^{-}}{d t}+\left[F(\lambda), S_{J}^{-}\right]=0, \quad i \frac{d T_{J}^{+}}{d t}+\left[F(\lambda), T_{J}^{+}\right]=0 \tag{84}
\end{equation*}
$$

### 8.2 The integrals of motion Hamiltonian properties of the MNLS eqs.

The block-diagonal Gauss factors $D_{J}^{ \pm}(\lambda)$ are generating functionals of the integrals of motion. The principal series of integrals is generated by $m_{1}^{ \pm}(\lambda)$ :

$$
\begin{equation*}
\pm \ln m_{1}^{ \pm}=\sum_{k=1}^{\infty} I_{k} \lambda^{-k} \tag{85}
\end{equation*}
$$

Let us outline a way to calculate their densities as functionals of $Q(x, t)$. Use a third type of Wronskian identities involving $\dot{\chi}^{ \pm}(x, \lambda)$. They have
the form:

$$
\begin{equation*}
\left.\left(\hat{\chi}^{ \pm} \dot{\chi}^{ \pm}(x, \lambda)+i J x\right)\right|_{x=-\infty} ^{\infty}=-i \int_{-\infty}^{\infty} d x(\hat{\chi} J \chi(x, \lambda)-J) \tag{86}
\end{equation*}
$$

which gives

$$
\begin{equation*}
\pm \frac{d}{d \lambda} \ln m_{1}^{ \pm}(\lambda)=-i \int_{-\infty}^{\infty} d x(\langle\chi(x, \lambda) J \hat{\chi} J\rangle-1) \tag{87}
\end{equation*}
$$

Note that in the integrand of the above equation we have in fact $\left\langle h_{1}^{ \pm}(x, \lambda) J\right\rangle$. Splitting $h_{1}^{ \pm}(x, \lambda)=h_{1}^{d, \pm}(x, \lambda)+\boldsymbol{h}_{1}^{ \pm}(x, \lambda)$ into 'block-diagonal' and 'block-off-diagonal' parts we get

$$
\begin{align*}
\left(\Lambda_{+}-\lambda\right) \boldsymbol{h}_{1}^{ \pm}(x, \lambda) & =i\left[\lim _{y \rightarrow \pm \infty} h_{1}^{d, \pm}(x, \lambda), \operatorname{ad}_{J}^{-1} Q(x)\right]  \tag{88}\\
& =i\left[J, \operatorname{ad}_{J}^{-1} Q(x)\right] \equiv Q(x)
\end{align*}
$$

i.e.

$$
\begin{array}{r}
\left(\Lambda_{ \pm}-\lambda\right) \boldsymbol{h}_{1}^{ \pm}(x, \lambda)=Q(x), \\
h_{1}^{d, \pm}(x, \lambda)=J+\int_{ \pm \infty}^{x} d y\left[Q(y), \boldsymbol{h}_{1}^{ \pm}(x, \lambda)\right] . \tag{89}
\end{array}
$$

Using eq. (89) and inverting formally the operator $\left(\Lambda_{ \pm}-\lambda\right)$ we obtain the relations:

$$
\begin{align*}
\pm \frac{d}{d \lambda} \ln m_{1}^{ \pm}(\lambda) & =-i \int_{-\infty}^{\infty} d x\left(\left\langle J+\int_{ \pm \infty}^{x} d y\left[Q(y), \boldsymbol{h}_{1}^{ \pm}(x, \lambda)\right], J\right\rangle-1\right) \\
& =-i \int_{-\infty}^{\infty} d x \int_{ \pm \infty}^{x} d y\left\langle[J, Q(y)], \boldsymbol{h}_{1}^{ \pm}(x, \lambda)\right\rangle \\
& =-i \int_{-\infty}^{\infty} d x \int_{ \pm \infty}^{x} d y\left\langle[J, Q(y)],\left(\Lambda_{ \pm}-\lambda\right)^{-1} Q(x)\right\rangle \tag{90}
\end{align*}
$$

This procedure allows us to express the integrals of motion as functionals of $Q(x)$ in compact form:

$$
\begin{equation*}
I_{s}=\frac{1}{s} \int_{-\infty}^{\infty} d x \int_{ \pm \infty}^{x} d y\left\langle[J, Q(y)], \Lambda_{ \pm}^{s} Q(x)\right\rangle \tag{91}
\end{equation*}
$$

Note: the operators $\Lambda_{+}$and $\Lambda_{-}$produce the same integrals of motion.

Using the explicit form of $\Lambda_{ \pm}$we find that:

$$
\begin{align*}
\Lambda_{ \pm} Q & =i \operatorname{ad}_{J}^{-1} \frac{d Q}{d x}=i \frac{d Q^{+}}{d x}-i \frac{d Q^{-}}{d x} \\
\Lambda_{ \pm}^{2} Q & =-\frac{d^{2} Q}{d x^{2}}+\left[Q^{+}-Q^{-},\left[Q^{+}, Q^{-}\right]\right], \\
\Lambda_{ \pm}^{3} Q & =-i \frac{d^{3} Q^{+}}{d x^{3}}+i \frac{d^{3} Q^{-}}{d x^{3}}+3 i\left[Q^{+},\left[Q_{x}^{+}, Q^{-}\right]\right]+3 i\left[Q^{-},\left[Q^{+}, Q_{x}^{-}\right]\right],  \tag{92}\\
& Q^{+}(x, t)=\left(\vec{q}(x, t) \cdot \vec{E}_{1}^{+}\right), \quad Q^{-}(x, t)=\left(\vec{p}(x, t) \cdot \vec{E}_{1}^{-}\right) .
\end{align*}
$$

Thus for the first three integrals of motion we get:

$$
\begin{align*}
& I_{1}=-i \int_{-\infty}^{\infty} d x\left\langle Q^{+}(x), Q^{-}(x)\right\rangle \\
& I_{2}=\frac{1}{2} \int_{-\infty}^{\infty} d x\left(\left\langle Q_{x}^{+}(x), Q^{-}(x)\right\rangle-\left\langle Q^{+}(x), Q_{x}^{-}(x)\right\rangle\right)  \tag{93}\\
& I_{3}=i \int_{-\infty}^{\infty} d x\left(-\left\langle Q_{x}^{+}(x), Q_{x}^{-}(x)\right\rangle+\frac{1}{2}\left\langle\left[Q^{+}(x), Q^{-}(x)\right],\left[Q^{+}(x), Q^{-}(x)\right]\right\rangle\right)
\end{align*}
$$

$i I_{1}$ - is the density of the particles, $I_{2}$ is the momentum and $-i I_{3}$ is the Hamiltonian of the MNLS equations. Indeed, taking $H_{(0)}=-i I_{3}$ with the Poissson brackets

$$
\begin{equation*}
\left\{q_{k}(y, t), p_{j}(x, t)\right\}=i \delta_{k j} \delta(x-y) \tag{94}
\end{equation*}
$$

coincide with the MNLS equations (15). The above Poisson brackets are dual to the canonical symplectic form:

$$
\begin{align*}
\Omega_{0} & =i \int_{-\infty}^{\infty} d x \operatorname{tr}(\delta \vec{p}(x) \wedge \delta \vec{q}(x)) \\
& =\frac{1}{i} \int_{-\infty}^{\infty} d x \operatorname{tr}\left(\operatorname{ad}_{J}^{-1} \delta Q(x) \wedge\left[J, \operatorname{ad}_{J}^{-1} \delta Q(x)\right)\right.  \tag{95}\\
& =\frac{1}{i}\left[\left[\operatorname{ad}_{J}^{-1} \delta Q(x) \wedge \operatorname{ad}_{J}^{-1} \delta Q(x)\right]\right], \tag{96}
\end{align*}
$$

The last expression for $\Omega_{0}$ is preferable to us because it makes obvious the interpretation of $\delta Q(x, t)$ as local coordinate on the co-adjoint orbit passing through $J$. It can be evaluated in terms of the scattering data
variations.

$$
\begin{aligned}
\Omega_{0} & =\frac{1}{\pi i} \int_{-\infty}^{\infty} d \lambda\left(\Omega_{0}^{+}(\lambda)-\Omega_{0}^{-}(\lambda)\right)-2 \sum_{j=1}^{N}\left(\underset{\lambda=\lambda_{j}^{+}}{\operatorname{Res}} \Omega_{0}^{+}(\lambda)+\underset{\lambda=\lambda_{j}^{-}}{\operatorname{Res}} \Omega_{0}^{-}(\lambda)\right), \\
\Omega_{0}^{ \pm}(\lambda) & =\sum_{\alpha, \gamma \in \Delta_{1}^{+}} \delta \tau^{ \pm}(\lambda) D_{\alpha, \gamma}^{ \pm} \wedge \delta \rho_{\gamma}^{ \pm}, \quad D_{\alpha, \gamma}^{ \pm}=\left\langle\hat{D}^{ \pm} E_{\mp \gamma} D^{ \pm}(\lambda) E_{ \pm \alpha}\right\rangle,
\end{aligned}
$$

Hierarchy of Hamiltonian formulations of MNLS:

$$
\begin{align*}
& \left.\Omega_{k}=\frac{1}{i}\left[\operatorname{ad}_{J}^{-1} \delta Q \wedge \Lambda^{k} \operatorname{ad}_{J}^{-1} \delta Q\right]\right], \quad \Lambda=\frac{1}{2}\left(\Lambda_{+}+\Lambda_{-}\right)  \tag{97}\\
& H_{k}=i^{k+3} I_{k+3} \tag{98}
\end{align*}
$$

We can also calculate $\Omega_{k}$ in terms of the scattering data variations. Doing this we will need also eqs. (79) and (80). The answer is

$$
\begin{equation*}
\Omega_{k}=\frac{1}{2 \pi i} \int_{-\infty}^{\infty} d \lambda \lambda^{k}\left(\Omega_{0}^{+}(\lambda)-\Omega_{0}^{-}(\lambda)\right)-i \sum_{j=1}^{N}\left(\Omega_{k, j}^{+}+\Omega_{k ; j}^{-}\right) \tag{99}
\end{equation*}
$$

$$
\begin{equation*}
\Omega_{k, j}^{ \pm}=\underset{\lambda=\lambda_{j}^{ \pm}}{\operatorname{Res}^{k} \Omega_{0}^{ \pm}(\lambda) . . . . . . .} \tag{100}
\end{equation*}
$$

This allows one to prove that if we are able to cast $\Omega_{0}$ in canonical form then all $\Omega_{k}$ will also be cast in canonical form and will be pair-wise equivalent.

## II. Equations with Coxeter type reduction

This reduction is of the form:

$$
C_{4}\left(U\left(\kappa_{4}(\lambda)\right)\right)=U(\lambda)
$$

$$
C_{4}\left(V\left(\kappa_{4}(\lambda)\right)\right)=V(\lambda)
$$

where $C_{4}$ is the Coxeter automorphism:

$$
C_{4}^{h}=\mathbb{1}, \quad \kappa_{4}(\lambda)=\omega \lambda, \quad \omega^{h}=1
$$

## 9 Recursion operator for generalized ZakharovShabat system with a $\mathbb{Z}_{h}$ Coxeter type reduction

Generalized Zakharov-Shabat system associated with a simple Lie algebra $\mathfrak{g}$ of rank $r$

$$
\begin{equation*}
L \psi=i \partial_{x} \psi+(q-\lambda J) \psi=0 \tag{101}
\end{equation*}
$$

where

$$
\begin{equation*}
q=\sum_{j=1}^{r} q_{j} H_{j}, \quad J=\sum_{\alpha \in \mathcal{A}} E_{\alpha} \tag{102}
\end{equation*}
$$

The generators $H_{j}$ for $j=1, \ldots, r$ and $E_{\alpha}$ for any root $\alpha \in \Delta$ represent Cartan-Weyl's basis of the algebra $\mathfrak{g}$. The subset $\mathcal{A} \subset \Delta$ is formed by all admissible roots, so

$$
\mathcal{A}=\left\{\alpha_{1}, \ldots, \alpha_{r}, \alpha_{0}\right\}
$$

where $\alpha_{0}$ is the minimal root of $\mathfrak{g}$
The above potential is obtained form a generic one by applying a $\mathbb{Z}_{h}$ reduction

$$
\begin{equation*}
\mathcal{C} q \mathrm{C}^{-1}=q, \quad \mathcal{C} J \mathcal{C}^{-1}=\frac{1}{\omega} J \tag{103}
\end{equation*}
$$

where

$$
\begin{equation*}
\omega=e^{\frac{2 \pi i}{h}}, \quad \mathcal{C}=\exp \left(-\frac{2 \pi i}{h} H_{\vec{\rho}_{0}}\right), \quad\left(\vec{\rho}_{0}, \alpha_{j}\right)=1 \tag{104}
\end{equation*}
$$

where $\alpha_{1}, \ldots, \alpha_{r}$ are the simple roots of $\mathfrak{g}$. Any root $\beta=\sum_{j=1}^{r} n_{j} \alpha_{j}$. Then

$$
\left(\beta, \vec{\rho}_{0}\right)=\sum_{j=1}^{r} n_{j}=\operatorname{ht}(\beta),
$$

i.e.

$$
\left(\alpha_{k}, \vec{\rho}_{0}\right)=1, \quad\left(\alpha_{0}, \vec{\rho}_{0}\right)=h-1 .
$$

Taking into account the famous formula

$$
e^{B} A e^{-B}=e^{\operatorname{ad}_{B}} A
$$

it follows

$$
\begin{equation*}
\mathcal{C} J \mathcal{C}^{-1}=\sum_{\alpha \in \mathcal{A}} \exp \left(-\frac{2 \pi i}{h}\right) E_{\alpha}=\omega^{-1} J \tag{105}
\end{equation*}
$$

Consider the algebra $\mathfrak{s l}(r+1)$. For $\mathfrak{s l}(r+1)$ we have

$$
\mathcal{A}=\left\{e_{i}-e_{i+1}, \quad i=1, \ldots, r ; \quad e_{r+1}-e_{1}\right\}
$$

Choosing $\alpha=e_{k}-e_{k+1}$ we obtain $\vec{\rho}_{0}=\sum_{j=1}^{r} \omega_{j}$. The minimal root is $\alpha=\alpha_{\text {min }}=e_{r+1}-e_{1}$.

The Coxeter automorphism has a finite order $h=n$, the so-called Coxeter number. Hence it induces a $\mathbb{Z}_{h}$ grading in $\mathfrak{g}$ as follows

$$
\begin{equation*}
\mathfrak{g}=\sum_{k=0}^{h-1} \mathfrak{g}^{k}, \quad \mathfrak{g}^{k}=\left\{X \in \mathfrak{g} ; \mathcal{C} X \mathcal{C}^{-1}=\omega^{k} J\right\} \tag{106}
\end{equation*}
$$

Comparing the reduction condition (103) with the definition of splitting of $\mathfrak{g}$ we see that

$$
\begin{equation*}
q \in \mathfrak{g}^{0}, \quad J \in \mathfrak{g}^{h-1} \tag{107}
\end{equation*}
$$


$0-60$

The $\mathbb{Z}_{h}$ reduction affects the spectral properties of $L$ - its continuous spectrum consists in $2 h$ rays $l_{a}(a=1, \ldots, 2 h)$ through the origin of coordinate system in the complex $\lambda$-plane. The angles between any adjacent rays are equal to $\pi / h$. The rays split into $2 h$ sectors $\Omega_{a}$. In each sector $\Omega_{a}$ there exists a fundamental analytic solution $\chi^{a}(x, \lambda)$. The fundamental analytic solutions of adjacent sectors are interrelated via a local RiemmanHilbert problem

$$
\begin{equation*}
\chi^{a}(x, \lambda)=\chi^{a-1}(x, \lambda) G^{a}(\lambda) . \tag{108}
\end{equation*}
$$

Thus with each sector is associated "squared"solutions as follows
$e_{\alpha}^{a}(x, \lambda)=\pi\left(\chi^{a}(x, \lambda) E_{\alpha} \hat{\chi^{a}}(x, \lambda)\right), \quad h_{j}^{a}(x, \lambda)=\pi\left(\chi^{a}(x, \lambda) H_{j} \hat{\chi^{a}}(x, \lambda)\right)$,
where $\pi: \mathfrak{g} \mapsto \mathfrak{g} / \operatorname{ker}\left(\operatorname{ad}_{J}\right)$. Introducing

$$
\begin{equation*}
\mathcal{E}_{\alpha}^{a}=\chi^{a} E_{\alpha} \hat{\chi^{a}}=e_{\alpha}^{a}+d_{\alpha}^{a}, \quad \mathcal{H}_{j}^{a}=\chi^{a} H_{j} \hat{\chi}^{a}=h_{j}^{a}+f_{j}^{a} . \tag{110}
\end{equation*}
$$

we immediately convince ourselves that

$$
\begin{equation*}
i \partial_{x} \mathcal{E}_{\alpha}^{a}+\left[q-\lambda J, \mathcal{E}_{\alpha}^{a}\right]=0 \tag{111}
\end{equation*}
$$

$$
\begin{equation*}
i \partial_{x} \mathcal{H}_{j}^{a}+\left[q-\lambda J, \mathcal{H}_{j}^{a}\right]=0 \tag{112}
\end{equation*}
$$

Further on we shall skip the upper index $a$ in the squared solutions for the sake of simplicity. After applying the splitting (110) to (111) we derive

$$
\begin{align*}
i \partial_{x} e_{\alpha}+\pi\left[q, e_{\alpha}\right]+\pi\left[q, d_{\alpha}\right] & =\lambda \pi\left[J, e_{\alpha}\right]  \tag{113}\\
i \partial_{x} d_{\alpha}+(\mathbb{1}-\pi)\left[q, e_{\alpha}\right] & =0 \tag{114}
\end{align*}
$$

Obviously, $e_{\alpha}$ and $d_{\alpha}$ possess the representation

$$
\begin{array}{ll}
e_{\alpha}(x, \lambda)=\sum_{k=0}^{h-1} e_{\alpha, k}(x, \lambda), & e_{\alpha, k}(x, \lambda) \in \mathfrak{g}^{k} \\
d_{\alpha}(x, \lambda)=\sum_{k=0}^{h-1} d_{\alpha, k}(x, \lambda), & d_{\alpha, k}(x, \lambda) \in \mathfrak{g}^{k}
\end{array}
$$

As a result we obtain the following equalities

$$
\begin{equation*}
i \partial_{x} e_{\alpha, 0}+\pi\left[q, e_{\alpha, 0}\right]=\lambda \pi\left[J, e_{\alpha, 1}\right] \tag{115}
\end{equation*}
$$

$$
\begin{equation*}
i \partial_{x} e_{\alpha, k}+\pi\left[q, e_{\alpha, k}\right]+\pi\left[q, d_{\alpha, k}\right]=\lambda \pi\left[J, e_{\alpha, k+1}\right] \tag{116}
\end{equation*}
$$

$k=1, \ldots, h-1$. Since $d_{\alpha}$ belongs to the centralizer $C_{J}$ of $J$ it is a linear combination of the following type

$$
\begin{equation*}
d_{\alpha}=\sum_{j=1}^{r} \mathbf{d}_{\alpha}^{j} \varepsilon_{j}, \quad \mathcal{E}_{j} \in \mathfrak{g}^{k_{j}}, \quad\left[J, \mathcal{E}_{j}\right]=0 \tag{117}
\end{equation*}
$$

Consider the $\mathfrak{s l}(r+1)$ case again $(h=r+1)$. Now the adapted basis has the form

$$
\mathcal{E}_{k}=J^{h-k} \in \mathfrak{g}^{k} .
$$

It follows from (114) that

$$
i \partial_{x} \mathbf{d}_{\alpha}^{k}+\frac{1}{h} \operatorname{tr}\left(\left[q, e_{\alpha}\right] J^{k}\right)=0, \quad \Rightarrow \mathbf{d}_{\alpha}^{k}=\frac{i}{h} \int_{ \pm \infty}^{x} d y \operatorname{tr}\left(\left[q, e_{\alpha}\right] J^{k}\right)
$$

On the other hand we have

$$
\begin{aligned}
& i \partial_{x} e_{\alpha, 0}+\pi\left[q, e_{\alpha, 0}\right]=\lambda \pi\left[J, e_{\alpha, 1}\right] \\
& i \partial_{x} e_{\alpha, k}+\frac{i}{h} \pi\left[q, J^{h-k}\right] \int_{ \pm \infty}^{x} d y \operatorname{tr}\left(\left[q, e_{\alpha, k}\right] J^{k}\right)+\pi\left[q, e_{\alpha, k}\right]=\lambda \pi\left[J, e_{\alpha, k+1}\right]
\end{aligned}
$$

As a result one obtains

$$
e_{\alpha, 1}=\frac{1}{\lambda} \Lambda_{0} e_{\alpha, 0}, \quad e_{\alpha, k+1}=\frac{1}{\lambda} \Lambda_{k} e_{\alpha, k}, \quad k=1, \ldots, h-1,
$$

where

$$
\begin{gathered}
\Lambda_{0}=\operatorname{ad}_{J}^{-1}\left(i \partial_{x}+\pi[q, .]\right) \\
\Lambda_{k}=\operatorname{ad}_{J}^{-1}\left(i \partial_{x}+\frac{i}{h} \pi\left(\left[q, J^{h-k}\right]\right) \int_{ \pm \infty}^{x} d y \operatorname{tr}\left([q, .] J^{k}\right)+\pi[q, .]\right) .
\end{gathered}
$$

Therefore

$$
\Lambda e_{\alpha, 0}=\lambda^{h} e_{\alpha, 0}, \quad \Lambda=\Lambda_{h-1} \Lambda_{h-2} \ldots \Lambda_{0}
$$

From Wronskian relations we get:

$$
\begin{array}{r}
q(x)=\frac{i}{2 \pi} \sum_{a=1}^{h}(-1)^{(a+1)} \beta_{a}(J) \int_{l_{a}} d \lambda \beta_{a}(J) \\
\left(s_{a, \beta_{a}}^{+} e_{\beta_{a}, 0}^{(a)}(x, \lambda)+s_{a,-\beta_{a}}^{-} e_{-\beta_{a}, 0}^{(a-1)}(x, \lambda)\right), \\
\operatorname{ad}_{J}^{-1}\left[J^{k}, q(x)\right]=\frac{i}{2 \pi} \sum_{a=1}^{h}(-1)^{(a+1)} \beta_{a}\left(J^{k}\right) \int_{l_{a}} d \lambda \beta_{a}(J) \\
\left(s_{a, \beta_{a}}^{+} e_{\beta_{a}, 0}^{(a)}(x, \lambda)+s_{a,-\beta_{a}}^{-} e_{-\beta_{a}, 0}^{(a-1)}(x, \lambda)\right), \\
\Lambda^{p} \operatorname{ad}_{J}^{-1}\left[J^{k}, q(x)\right]=\frac{i}{2 \pi} \sum_{a=1}^{h}(-1)^{(a+1)} \beta_{a}\left(J^{k}\right) \int_{l_{a}} d \lambda \lambda^{h p} \\
\left(s_{a, \beta_{a}}^{+} e_{\beta_{a}, 0}^{(a)}(x, \lambda)+s_{a,-\beta_{a}}^{-} e_{-\beta_{a}, 0}^{(a-1)}(x, \lambda)\right),
\end{array}
$$

and

$$
\operatorname{ad}_{J}^{-1} \delta q(x)=\frac{i}{2 \pi} \sum_{a=1}^{h}(-1)^{a} \int_{l_{a}} d \lambda\left(\delta s_{a, \beta_{a}}^{+} e_{\beta_{a}, h-1}^{(a)}(x, \lambda)-\delta s_{a,-\beta_{a}}^{-} e_{-\beta_{a}, h-1}^{(a-1)}(x, \lambda)\right) .
$$

If $\delta q(x) \simeq q(x, t+\delta t)-q(x, t)=q_{t} \delta t+\mathcal{O}\left((\delta t)^{2}\right)$, then
$\operatorname{ad}_{J}^{-1} q_{t}(x)=\frac{i}{2 \pi} \sum_{a=1}^{h}(-1)^{a} \int_{l_{a}} d \lambda\left(s_{a, \beta_{a} ; t}^{+} e_{\beta_{a}, h-1}^{(a)}(x, \lambda)-s_{a,-\beta_{a} ; t}^{-} e_{-\beta_{a}, h-1}^{(a-1)}(x, \lambda)\right)$.
Therefore the NLEE:

$$
i \Lambda_{h-1} \operatorname{ad}_{J}^{-1} q_{t}+\sum_{k} c_{k} \Lambda_{h} \Lambda_{h-1} \ldots \Lambda_{k} \operatorname{ad}_{J}^{-1}\left[J^{k}, q(x, t)\right]=0,
$$

is equivalent to the linear evolution eqs. for $s_{a, \beta_{a}}^{+}$:

$$
i \frac{d s_{a, \beta_{a}}^{+}}{d t} \pm \sum_{k} c_{k} \lambda^{h-k+1} \beta_{a}\left(J^{k}\right) s_{a, \beta_{a}}^{+}(\lambda, t)=0
$$

## Examples of such NLEE:

The two-dimensional Toda field theory (Mikhailov, 1979):

$$
\begin{aligned}
& \quad \frac{\partial^{2} u_{k}}{\partial x \partial t}=\exp \left(u_{k+1}-u_{k}\right)-\exp \left(u_{k}-u_{k-1}\right), \quad k=1, \ldots, h \\
& u_{0} \equiv u_{h} \\
& \mathbb{Z}_{h} \text {-NLS eq.: }
\end{aligned}
$$

$$
\begin{equation*}
i u_{k, t}+\gamma\left(\frac{\pi k}{N} \cdot u_{k, x}+i \sum_{p=1}^{N-1} u_{p} u_{k-p}\right)_{x}=0, \quad k=1,2, \ldots, N-1 \tag{119}
\end{equation*}
$$

## Благодаря

Thank you

За for

вниманието attention!

