GRADED GEOMETRY IN MECHANICS AND FIELD THEORY

Janusz Grabowski

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XXIX International Conference Geometry, Integrability and Quantization Varna, 2-7 June, 2017

Literature

The talk is based on some ideas of W. M. Tulczyjew and my collaboration with A. Bruce, K. Grabowska, and M. Rotkiewicz:

- Grabowski-Rotkiewicz, Graded bundles and homogeneity structures,
 J. Geom. Phys. 62 (2012), 21–36.
- Bruce-Grabowska-Grabowski, Higher order mechanics on graded bundles, J. Phys. A 48 (2015), 205203 (32pp).
- Bruce-Grabowska-Grabowski, Graded bundles in the category of Lie groupoids, SIGMA 11 (2015), 090, (25pp).
- Bruce-Grabowska-Grabowski, Linear duals of graded bundles and higher analogues of (Lie) algebroids, J. Geom. Phys. 101 (2016), 71–99.
- Bruce-Grabowski-Rotkiewicz, Polarisation of graded bundles, SIGMA 12 (2016), 106, (30pp).

• A vector bundle is a locally trivial fibration $\tau: E \to M$ which, locally over $U \subset M$, reads $\tau^{-1}(U) \simeq U \times \mathbb{R}^n$ and admits an atlas in which local trivializations transform linearly in fibers

$$U \cap V \times \mathbb{R}^n \ni (x, y) \mapsto (x, A(x)y) \in U \cap V \times \mathbb{R}^n$$

 $A(x) \in \mathrm{GL}(n,\mathbb{R}).$

- The latter property can also be expressed in the terms of the gradation in which base coordinates x have degrees 0 and 'linear coordinates' y have degree 1. Linearity in y is now equivalent to the fact that changes of coordinates respect the degrees.
- Morphisms in the category of vector bundles are represented by commutative diagram of smooth maps



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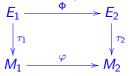
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$$U \cap V \times \mathbb{R}^n \ni (x, y) \mapsto (x, A(x, y)) \in U \cap V \times \mathbb{R}^n$$

- One can show that in this case A(x, y) must be polynomial in fiber coordinates, i.e. any graded bundle is a polynomial bundle.
- As these polynomials need not to be linear, graded bundles do not have, in general, vector space structure in fibers. For instance, if $(y,z) \in \mathbb{R}^2$ are coordinates of degrees 1,2, respectively, then the map $(y,z) \mapsto (y,z+y^2)$ is a diffeomorphism preserving the degrees, but it is nonlinear.
- If all $w_i \leq r$, we say that the graded bundle is of degree r.

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• A straightforward generalization is the concept of a graded bundle $\tau: F \to M$ with a local trivialization by $U \times \mathbb{R}^n$ as before, and with the difference that the local coordinates (y^1, \ldots, y^n) in the fibres have now associated positive integer weights $w_1, \ldots, w_n \in \mathbb{N}$, that are preserved by changes of local trivializations:

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- Vector bundles are just graded bundles of degree 1.
- Canonical example: $T^k M \to M$ is a graded bundle of degree k with canonical coordinates $(x, \dot{x}, \ddot{x}, \ddot{x}, \dots)$ of degrees 0, 1, 2, 3, etc.

$$\begin{aligned} x'^{A} &= x'^{A}(x) \\ \dot{x}'^{A} &= \frac{\partial x'^{A}}{\partial x^{B}}(x)\dot{x}^{B} \\ \ddot{x}'^{A} &= \frac{\partial x'^{A}}{\partial x^{B}}(x)\ddot{x}^{B} + \frac{\partial^{2}x'^{A}}{\partial x^{B}\partial x^{C}}(x)\dot{x}^{B}\dot{x}^{C} \,. \end{aligned}$$

• Graded bundles F_k of degree k admit, like jet bundles, a tower of affine fibrations by reductions to coordinates of lower degrees

$$F_k \xrightarrow{\tau^k} F_{k-1} \xrightarrow{\tau^{k-1}} \cdots \xrightarrow{\tau^3} F_2 \xrightarrow{\tau^2} F_1 \xrightarrow{\tau^1} F_0 = M$$

 Note that similar objects has been used in supergeometry by Ševera, Voronov, Roytenberg et al. under the name N-manifolds. However, we will work with classical, purely even manifolds during this talk.

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$$\nabla_F = \sum_a w_a y^a \partial_{y^a}.$$

- The flow of the weight vector field extends to a smooth action $\mathbb{R} \ni t \mapsto h_t$ of multiplicative reals on F, $h_t(x^\mu, y^a) = (x^\mu, t^{w_a}y^a)$. Such an action $h: \mathbb{R} \times F \to F$, $h_t \circ h_s = h_{ts}$, we will call a homogeneity structure.
- A function $f: F \to \mathbb{R}$ is called homogeneous of degree (weight) k if $\nabla_F(f) = k f$, or equivalently $f(h_t(x)) = t^k f(x)$.
- Note that for graded bundles only non-negative integer degrees of homogeneity are allowed. This is not true for more general 'graded manifolds': for F=(0,1), with the coordinate x of degree 1, the function x^a is homogeneous of degree a for all $a \in \mathbb{R}$.

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• With the use of coordinates (x^{α}, y^{a}) with degrees 0 for basic coordinates x^{α} , and degrees $w_{a} > 0$ for the fibre coordinates y^{a} , we can define on the graded bundle F a globally defined weight vector field (Euler vector field)

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The fundamental fact (cf. [Grabowski-Rotkiewicz]) says that graded bundles and homogeneity structures are in fact equivalent concepts. There is namely a canonical isomorphism of the category of graded bundles and the category of homogeneity structures. This is because any manifold equipped with a homogeneity structure admits an atlas consisting of homogeneous functions.

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Morphisms of two homogeneity structures (F^i, h^i) , i = 1, 2, are defined as smooth maps $\Phi: F^1 \to F^2$ intertwining the \mathbb{R} -actions: $\Phi \circ h^1_t = h^2_t \circ \Phi$. Consequently, a homogeneity substructure is a smooth submanifold S invariant with respect to h, $h_t(S) \subset S$.

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- We can extend the concept of a double vector bundle of Pradines and Mackenzie to double graded bundles.
- However, thanks to the simple description in terms of a homogeneity structure, the categorial and 'diagrammatic' definition can be substantially simplified.
- As two graded bundle structure on the same manifold are just two homogeneity structures, the obvious concept of compatibility leads to the following: A double graded bundle is a manifold equipped with two homogeneity structures h¹, h² which are compatible in the sense that

$$h^1_t \circ h^2_s = h^2_s \circ h^1_t \quad ext{for all } s,t \in \mathbb{R} \,.$$

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- Lifts. If $\tau : F \to M$ is a graded bundle of degree k, then TF and T^*F carry canonical double graded bundle structure: one is the obvious vector bundle, the other is of degree k.
- The above examples are double graded bundle whose one structure is linear. We will call such structures GrL-bundles.
- There are also lifts of graded structures on F to T^rF .
- In particular, if τ : E → M is a vector bundle, then TE and T*E are double vector bundles. The latter is isomorphic with T*E* (Tulczyjew, Mackenzie & Xu), with an isomorphism

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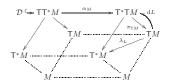
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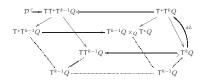


Motivation - higher order mechanics

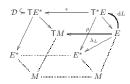
First order Lagrangian mechanics



k-th order Lagrangian mechanics



Reduction w.r.t. symmetry



reduced ...



Any $\mathcal{D} \subset \mathsf{TN}$ can be viewed as implicit dynamics whose solutions are curves $\gamma : \mathbb{R} \to \mathsf{N}$ s.t. $\dot{\gamma} \in \mathcal{D}$. For the lagrangian phase equations:

M - positions, TM - (kinematic) configurations, $L:TM \to \mathbb{R}$ - Lagrangiar T^*M - phase space

$$\mathcal{D} = \varepsilon_M(\mathsf{d}L(\mathsf{T}M))) = \mathcal{T}L(\mathsf{T}M)\,,$$

the image of the Tulczyjew differential TL, is the phase dynamics

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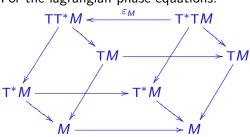
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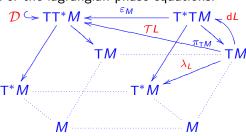
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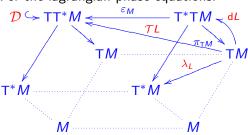
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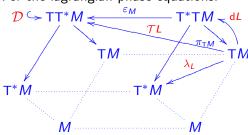
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whence the Euler-Lagrange equation: $\frac{\partial L}{\partial x} = \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{x}} \right)$. Note that L can be as well singular for the price that \mathcal{D} is an implicit equation.

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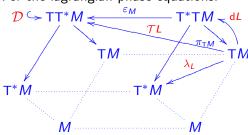
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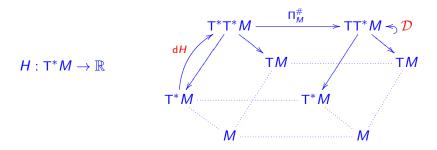


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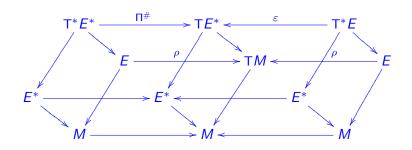
The Tulczyjew triple - Hamiltonian side



$$\mathcal{D} = \Pi_M^{\#}(dH(T^*M))$$

$$\mathcal{D} = \left\{ (x, p, \dot{x}, \dot{p}) : \dot{p} = -\frac{\partial H}{\partial x}, \dot{x} = \frac{\partial H}{\partial p} \right\},$$

whence the Hamilton equations.



$$H: E^* \longrightarrow \mathbb{R}$$

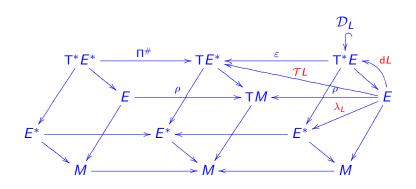
$$\mathcal{D}_H \subset \mathsf{T}^*E^*$$

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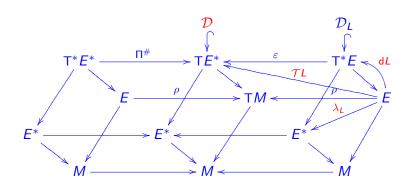
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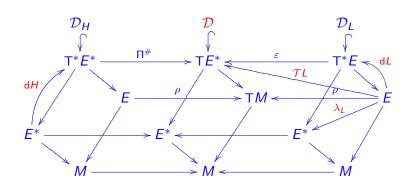
$$\mathcal{D}_H \subset \mathsf{T}^*E^{\mathsf{T}}$$

$$\mathcal{D} = \mathcal{T}L(E)$$

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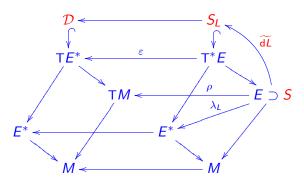
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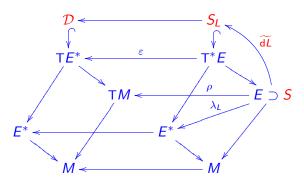
$$\mathcal{D}_L\subset \mathsf{T}^*E$$



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$$S_L = \{ \alpha_e \in \mathsf{T}_e^* E : e \in S \text{ and } \langle \alpha_e, v_e \rangle = \mathsf{d}L(v_e) \text{ for every } v_e \in \mathsf{T}_e S \}.$$

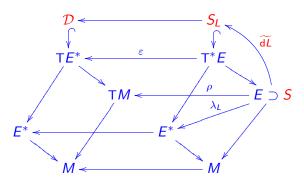
The vakonomically constrained phase dynamics is just $\mathcal{D} = \varepsilon(S_L) \subset \mathsf{T}E^*$.



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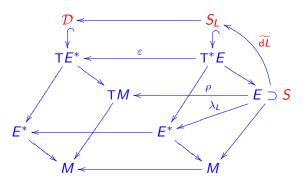
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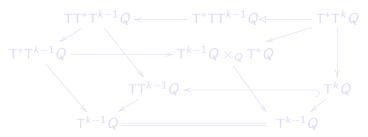
The vakonomically constrained phase dynamics is just $\mathcal{D} = \varepsilon(S_L) \subset TE^*$.

Higher order Lagrangians

The mechanics with a higher order Lagrangian $L: \mathsf{T}^k Q \to \mathbb{R}$ is traditionally constructed as a vakonomic mechanics, thanks to the canonical embedding of the higher tangent bundle $\mathsf{T}^k Q$ into the tangent bundle $\mathsf{T}^{k-1} Q$ as an affine subbundle of holonomic vectors:

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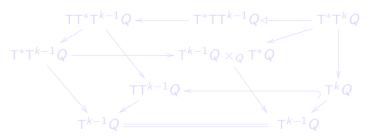


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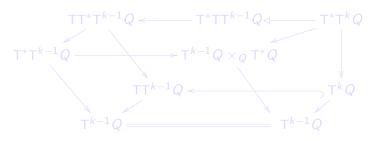
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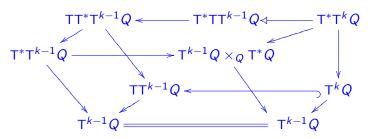
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The possibility of constructing mechanics on graded bundles is based on the following generalization of the embedding $T^kQ \hookrightarrow TT^{k-1}Q$.

Theorem (Bruce-Grabowska-Grabowski)

There is a canonical linearization functor $I: GrB \to GrL$ from the category of graded bundles into the category of GrL-bundles which assigns, for an arbitrary graded bundle F_k of degree k, a canonical GrL-bundle $I(F_k)$ of bi-degree (k-1,1) which is linear over F_{k-1} , called the linearization of F_k , together with a graded embedding $\iota: F_k \hookrightarrow I(F_k)$ of F_k as an affine subbundle of the vector bundle $I(F_k) \to F_{k-1}$.

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The linearisation of the graded bundle $A^k(\mathcal{G})$ is given as

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inherits graded bundle structure of degree k as a graded subbundle of $T^k \mathcal{G}$. Of course, $A = A^1(\mathcal{G})$ can be identified with the Lie algebroid of \mathcal{G} .

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The linearisation of the graded bundle $A^k(\mathcal{G})$ is given as

$$I(A^k(\mathcal{G})) \simeq \{(Y,Z) \in A(\mathcal{G}) \times_M TA^{k-1}(\mathcal{G}) | \quad \rho(Y) = T\tau(Z)\},$$

viewed as a vector bundle over $A^{k-1}(\mathcal{G})$ with respect to the obvious projection of part Z onto $A^{k-1}(\mathcal{G})$. Here, $\rho:A(\mathcal{G})\to TM$ is the standard anchor of the Lie algebroid and $\tau:A^{k-1}(\mathcal{G})\to M$ is the obvious projection. Moreover, the above bundle is canonically a weighted Lie algebroid, a Lie algebroid prolongation in the sense of Popescu and Martínez.

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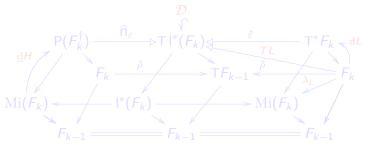
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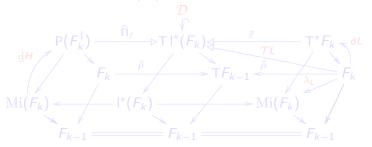
A weighted Lie algebroid on $I(F_k)$ gives the Tulczyjew triple



Here, the diagram consists of relations, $\hat{\varepsilon}: \mathsf{T}^*F_k \longrightarrow \mathsf{T}^*\mathsf{I}(F_k) \to \mathsf{T}\mathsf{I}^*(F_k)$, and $\mathsf{Mi}(F_k) = F_{k-1} \times_M \bar{F}_k$ is the so called Mironian of F_k . In the classical case, $\mathsf{Mi}(\mathsf{T}^kM) = \mathsf{T}^{k-1}M \times_M \mathsf{T}^*M$. $\mathcal{T}L$ is the Tulczyjew differential and λ_L the Legendre relation.

What replaces Lie algebroids in this version of higher Lagrangian theory are linearizations of graded bundles equipped with weighted Lie algebroid structures (weighted Lie algebroids on symmetric GrL-bundles).

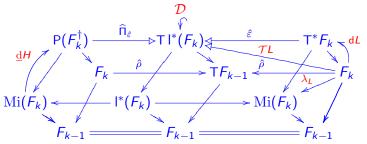
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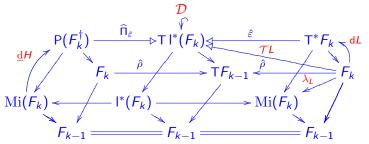
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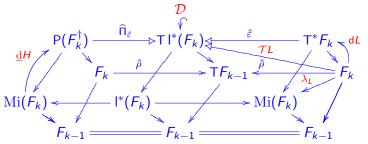
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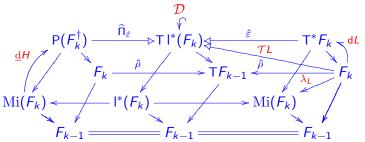


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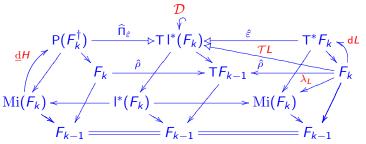
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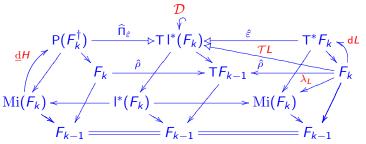
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Lagrangian framework for graded bundles

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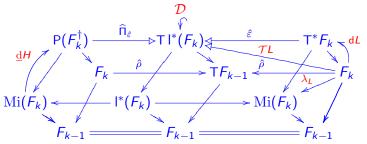


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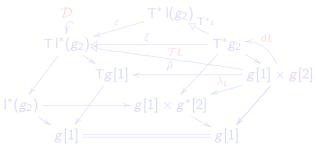
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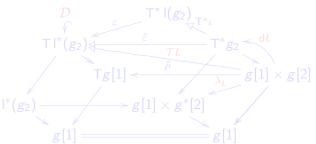
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Let g be a Lie algebra and put $F_2 = g_2 = g[1] \times g[2]$, with coordinates (x^i, z^j) on g_2 and coordinates (x^i, y^j, z^k) on $I(g_2) = g[1] \times g[1] \times g[2]$. The vector bundle projection is $\tau(x, y, z) = x$ and the corresponding diagram looks like



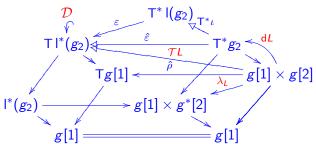
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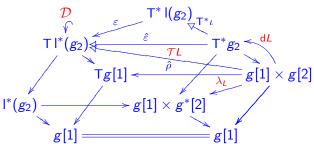
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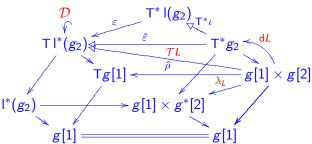
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so $\hat{\varepsilon}$ relates $(x, z, \alpha + \beta, \gamma)$ with $(x, \beta, \gamma, z, ad_x^*\beta, \alpha)$.

Given a Lagrangian $L: g_2 \to \mathbb{R}$, the Tulczyjew differential relation $TL: g_2 \to TL^*(g_2)$ therefore reads

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Hence, for the phase dynamics

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$$J_j \ddot{x}^j = \sum_{i,k} c^k_{ij} I_k x^i \ddot{x}^k .$$

This leads to the Euler-Lagrange equations on g_2 :

$$\dot{x} = z,$$

$$\frac{d}{dt} \left(\frac{\partial L}{\partial x}(x, z) - \frac{d}{dt} \left(\frac{\partial L}{\partial z}(x, z) \right) \right) = \operatorname{ad}_{x}^{*} \left(\frac{\partial L}{\partial x}(x, z) - \frac{d}{dt} \left(\frac{\partial L}{\partial z}(x, z) \right) \right)$$

These equations are second order and induce the Euler-Lagrange equations on g which are of order 3:

$$\frac{d}{dt} \left(\frac{\partial L}{\partial x} (x, \dot{x}) - \frac{d}{dt} \left(\frac{\partial L}{\partial z} (x, \dot{x}) \right) \right) = \operatorname{ad}_{x}^{*} \left(\frac{\partial L}{\partial x} (x, \dot{x}) - \frac{d}{dt} \left(\frac{\partial L}{\partial z} (x, \dot{x}) \right) \right).$$

For instance, the 'free' Lagrangian $L(x,z) = \frac{1}{2} \sum_i I_i(z^i)^2$ induces the equations on $g(c_{ii}^k)$ are structure constants, no summation convention):

$$J_j \ddot{x}^j = \sum_{i,k} c^k_{ij} I_k x^i \ddot{x}^k.$$

The latter can be viewed as 'higher Euler equations'.

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$$\frac{d}{dt}\left(\frac{\partial L}{\partial x}(x,\dot{x}) - \frac{d}{dt}\left(\frac{\partial L}{\partial z}(x,\dot{x})\right)\right) = \operatorname{ad}_{x}^{*}\left(\frac{\partial L}{\partial x}(x,\dot{x}) - \frac{d}{dt}\left(\frac{\partial L}{\partial z}(x,\dot{x})\right)\right).$$

For instance, the 'free' Lagrangian $L(x,z) = \frac{1}{2} \sum_i I_i(z^i)^2$ induces the equations on $g(c_i^k)$ are structure constants, no summation convention):

$$I_j \ddot{x}^j = \sum_{i,k} c_{ij}^k I_k x^i \ddot{x}^k.$$

The latter can be viewed as 'higher Euler equations'.

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This leads to the Euler-Lagrange equations on g_2 :

$$\dot{x} = z,$$

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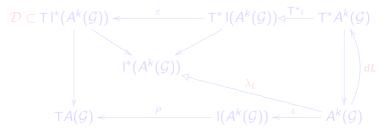
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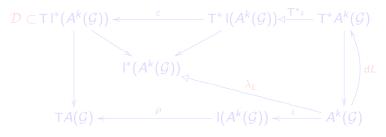


Here, $I(A^k(\mathcal{G}))$ is the corresponding Lie algebroid prolongation, $\mathcal{D} = \varepsilon \circ r \circ dL(A^k(\mathcal{G}))$, and λ_L is the Legendre relation.

Note that we deal with reductions: in the case $\mathcal G$ is a Lie group,

$$A^k(\mathcal{G}) = \mathsf{T}^k(\mathcal{G})/\mathcal{G}$$
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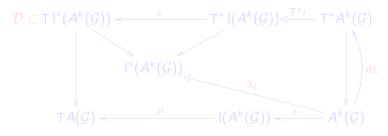
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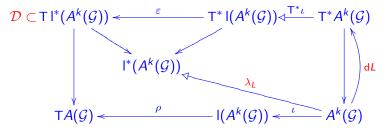


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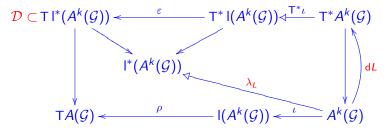
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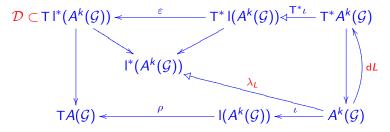
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$$(k-1)\pi_{b}^{2} = \frac{\partial L}{\partial y_{k-1}^{b}} - \frac{1}{k} \frac{d}{dt} \left(\frac{\partial L}{\partial y_{k}^{b}} \right),$$

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which we recognise as the Jacobi-Ostrogradski momenta.

$$\frac{d}{dt}\pi_a^k = \rho_a^A(x)\frac{\partial L}{\partial x^A} + y_1^b C_{ba}^c(x)\pi_c^k \,,$$

$$\rho_a^A(x)\frac{\partial L}{\partial x^A} = \left(\delta_a^c \frac{d}{dt} - y_1^b C_{ba}^c(x)\right) \left(\frac{\partial L}{\partial y_1^c} - \frac{1}{2!} \frac{d}{dt} \left(\frac{\partial L}{\partial y_2^c}\right) \cdots - (-1)^k \frac{1}{k!} \frac{d^{k-1}}{dt^{k-1}} \left(\frac{\partial L}{\partial y_k^c}\right)\right)$$

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$$\rho_{a}^{A}(x)\frac{\partial L}{\partial x^{A}} = \delta \left(\delta_{a}^{c}\frac{d}{dt} - y_{1}^{b}C_{ba}^{c}(x)\right) \left(\frac{\partial L}{\partial y_{1}^{c}} - \frac{1}{2!}\frac{d}{dt}\left(\frac{\partial L}{\partial y_{2}^{c}}\right) \cdots - (-1)^{k}\frac{1}{k!}\frac{d^{k-1}}{dt^{k-1}}\left(\frac{\partial L}{\partial y_{k}^{c}}\right)\right)$$

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which we define to be the k-th order Euler–Lagrange equations on $A(\mathcal{G})$

The above higher order algebroid Euler-Lagrange equations are in complete agreement with the ones obtained by Jóźwikowski & Rotkiewicz, Colombo & de Diego, as well as Martínez. We clearly recover the standard higher Euler-Lagrange equations on $\mathsf{T}^k M$ as a particular example.

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The above higher order algebroid Euler-Lagrange equations are in complete agreement with the ones obtained by Jóźwikowski & Rotkiewicz, Colombo & de Diego, as well as Martínez. We clearly recover the standard higher Euler-Lagrange equations on T^kM as a particular example.

The remaining equation for the dynamics is

$$\frac{d}{dt}\pi_a^k = \rho_a^A(x)\frac{\partial L}{\partial x^A} + y_1^b C_{ba}^c(x)\pi_c^k,$$

where ρ_a^A and C_{ba}^c are structure functions of the Lie algebroid $A=A(\mathcal{G})$. The above equation can then be rewritten as

$$\rho_{a}^{A}(x)\frac{\partial L}{\partial x^{A}} = \left(\delta_{a}^{c}\frac{d}{dt} - y_{1}^{b}C_{ba}^{c}(x)\right)\left(\frac{\partial L}{\partial y_{1}^{c}} - \frac{1}{2!}\frac{d}{dt}\left(\frac{\partial L}{\partial y_{2}^{c}}\right) \cdots - (-1)^{k}\frac{1}{k!}\frac{d^{k-1}}{dt^{k-1}}\left(\frac{\partial L}{\partial y_{k}^{c}}\right)\right)$$

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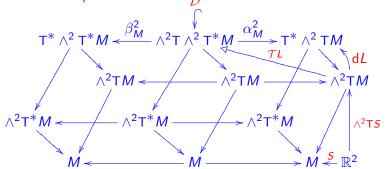
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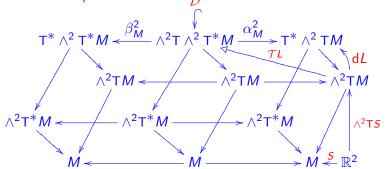
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A surface $S:(t,s)\mapsto (x^{\sigma}(t,s))$ in M satisfies the Euler-Lagrange equations if the image by $\mathrm{d}L$ of its prolongation to $\wedge^2\mathsf{T}M$,

$$(t,s)\mapsto \left(x^{\sigma}(t,s),\dot{x}^{\mu\nu}=rac{\partial x^{\mu}}{\partial t}rac{\partial x^{\nu}}{\partial s}-rac{\partial x^{\mu}}{\partial s}rac{\partial x^{\nu}}{\partial t}
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is α_M^2 -related to an admissible surface, i.e. the prolongation of a surface living in the phase space $\wedge^2 T^*M$ to $\wedge^2 T \wedge^2 T^*M$.

$$\dot{x}^{\mu\nu} = \frac{\partial x^{\mu}}{\partial t} \frac{\partial x^{\nu}}{\partial s} - \frac{\partial x^{\mu}}{\partial s} \frac{\partial x^{\nu}}{\partial t},
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$$(1+z_x^2)z_{yy}-2z_xz_yz_{xy}+(1+z_y^2)z_{xx}=0.$$

Euler-Lagrange equations for the Nambu-Goto Lagrangian, 📑 🗎 📜

J.Grabowski (IMPAN) **Graded Geometry** 28 / 29

In particular, if $M = \mathbb{R}^3 = \{(x^1 = x, x^2 = y, x^3 = z)\}$ with the Euclidean metric, the canonically induced 'free' Lagrangian on $\wedge^2 TM$ reads

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The Euler-Lagrange equation for surfaces being graphs $(x,y)\mapsto (x,y,z(x,y))$ provides the well-known equation for minimal surfaces, found already by Lagrange :

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THANK YOU FOR YOUR ATTENTION!