

The Helfrich model for the elasticity of biomembranes as a limit of mesoscopic energies

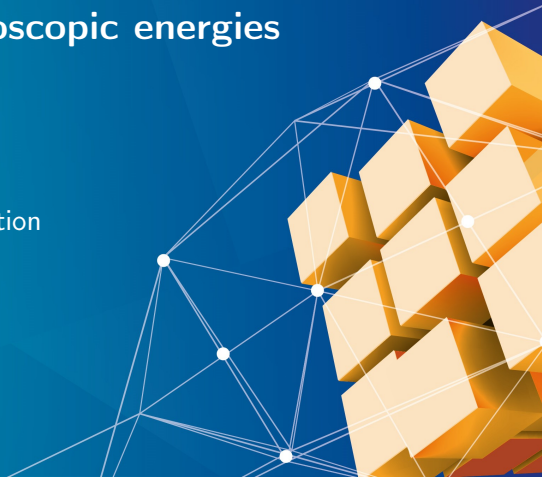
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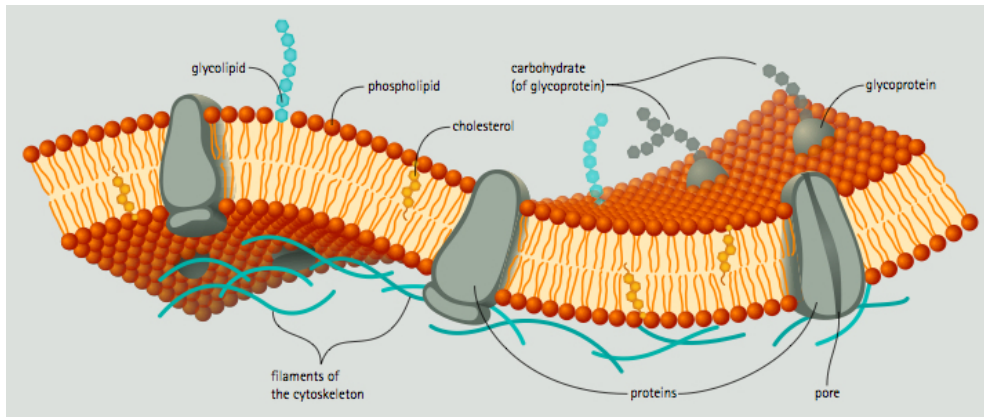
Outline

- Cell membranes
- Models for cell membranes
- Qualitative description of the Peletier-Röger mesoscopic model
- How to pass to the limit in a rigorous way: Γ -convergence
- Main tools for the 3D-analysis

References:

- L. Lussardi, M.A. Peletier and M. Röger, *Variational analysis of a mesoscale model for bilayer membranes*, J. Fixed Point Theory Appl. 15 (2014), no. 1, 217-240
- L. Lussardi and M. Röger, *Gamma convergence of a family of surface-director bending energies with small tilt*, Arch. Rational Mech. Anal. 219 (2016), no. 3, 985-1016

The cell membrane



The Helfrich energy functional (1973)

For a smooth surface S in the space we let

$$E(S) = \int_S \kappa_b (H_S - H_0)^2 - \kappa_G K_S d\sigma$$

- H_S is the mean curvature of S and K_S is the Gauss curvature of S
- $\kappa_b > \kappa_G > 0$ (Mathematics & Physics)
- H_0 is the spontaneous curvature

The shape of the cell membrane minimizes E

We notice that if S is a closed surface and $H_0 = 0$ then E reduces (up to constants) to the Willmore energy functional

$$W(S) = \int_S H_S^2 d\sigma$$

A microscopic model (Peletier-Röger, ARMA 2009)

Probabilistic model:

- In $\Omega \subset \mathbb{R}^d$: positions of heads X_h^i , tails X_t^i and water particles X_w^j , with $i = 1, \dots, N_\ell$ and $j = 1, \dots, N_w$. Set $\mathcal{X} := \Omega^{2N_\ell + N_w}$ and

$$\mathcal{X} \ni X = (X_t^1, \dots, X_t^{N_\ell}, X_h^1, \dots, X_h^{N_\ell}, X_w^1, \dots, X_w^{N_w})$$

- Probability density ψ on \mathcal{X} :

$$\psi: \mathcal{X} \rightarrow [0, 1], \quad \int \psi = 1$$

- Volume fractions of heads/tails/water:

$$r_t(\psi)(x), \quad r_h(\psi)(x), \quad r_w(\psi)(x)$$

A microscopic model (Peletier-Röger, ARMA 2009)

Energy contributions:

- Penalize the proximity of hydrophilic and hydrophobic grains:

$$\int \int (r_w(\psi)(x) + r_h(\psi)(x)) r_t(\psi)(y) \rho(x - y) dx dy$$

- Incompressibility:

$$r_t(\psi)(x) + r_h(\psi)(x) + r_w(\psi)(x) = 1$$

- Interaction between head and tail:

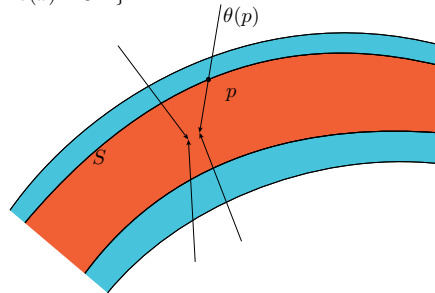
$$\int_{\mathcal{X}} \sum_{i=1}^{N_\ell} |X_h^i - X_t^i| \psi(X) dX$$



The mesoscopic model formally derived (Peletier-Röger, ARMA 2009)

$\{x : u(x) = \varepsilon^{-1}\}$

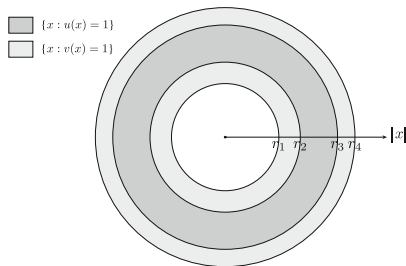
$\{x : v(x) = \varepsilon^{-1}\}$



- Energy arising from hydrophilic/hydrophobic behavior: area of the boundary of the region occupied by u_ε
- Energy arising from the covalent bond between heads and tails: Monge-Kantorovich distance between u_ε and v_ε



The behavior of the energy on ring structures



$$\text{Energy} \sim 2M + \underbrace{\frac{M}{4} \left(\frac{r_4 - r_1}{2\varepsilon} - 2 \right)^2}_{\text{partial localization}} + \underbrace{\frac{M\varepsilon^2}{(r_4 + r_1)^2}}_{\text{bending energy}}$$

We thus study $G_\varepsilon(u_\varepsilon, v_\varepsilon) := (\text{Energy} - 2M)/\varepsilon^2$

What happens as $\varepsilon \rightarrow 0$? A review on Γ -convergence

Approximate energies by means of simpler functionals with a stability property of the minimum problems during the limit process. General framework:

Γ -convergence (De Giorgi, 1975). If (X, d) is a metric space,

$F_\varepsilon: (X, d) \rightarrow [-\infty, +\infty]$, $F_\varepsilon \xrightarrow{\Gamma} F$ as $\varepsilon \rightarrow 0$ if

- $\forall u \in X, \forall u_\varepsilon \rightarrow u:$

$$F(u) \leq \liminf_{\varepsilon \rightarrow 0} F_\varepsilon(u_\varepsilon)$$

- $\forall u \in X, \exists u_\varepsilon \rightarrow u:$

$$\limsup_{\varepsilon \rightarrow 0} F_\varepsilon(u_\varepsilon) \leq F(u)$$

Why does Γ -convergence work?

$$\left. \begin{array}{l} F_\varepsilon \xrightarrow{\Gamma} F \\ F_\varepsilon(u_\varepsilon) = \min_X F_\varepsilon \\ u_\varepsilon \rightarrow u_0 \end{array} \right\} \Rightarrow \left\{ \begin{array}{l} F(u_0) = \min_X F \\ \min_X F_\varepsilon \rightarrow \min_X F \end{array} \right.$$



The main estimate (L-Peletier-Röger, JFPTA 2014)

S_ε := interface between u_ε and v_ε (smooth enough), then

$$G_\varepsilon(u_\varepsilon, v_\varepsilon) \gtrsim \frac{1}{\varepsilon^2} \int_{S_\varepsilon} \left(\frac{1}{\theta_\varepsilon \cdot \nu_\varepsilon} - 1 \right)^2 d\sigma \\ + \int_{S_\varepsilon} \frac{1}{4(\theta_\varepsilon \cdot \nu_\varepsilon)^3} (\lambda_\varepsilon^{(1)} + \lambda_\varepsilon^{(2)})^2 - \frac{1}{6} \lambda_\varepsilon^{(1)} \lambda_\varepsilon^{(2)} d\sigma$$

where:

- ν_ε is an orientation on S_ε and $\theta_\varepsilon \cdot \nu_\varepsilon > 0$ on S_ε
- $\lambda_\varepsilon^{(1)}, \lambda_\varepsilon^{(2)}$ are the eigenvalues of the covariant derivative of θ_ε

This estimate suggests that the limit energy should take the form

$$\int_S \frac{1}{4} H_S^2 - \frac{1}{6} K_S d\sigma$$



Generalized surfaces (Geometric Measure Theory)

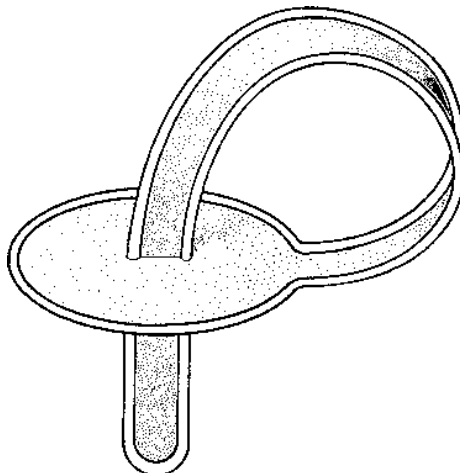
- PDEs/Classical variational problem \rightarrow weak notion of function
- Geometric variational problem \rightarrow weak notion of surface

smooth objects	weak objects
functions	distributions
surfaces	currents, varifolds, ...

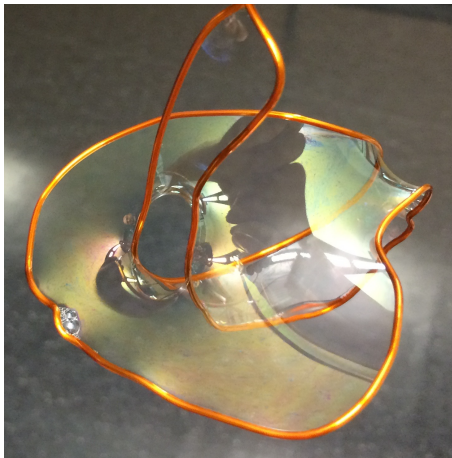
By definition:

- Currents: dual of the space of test differential forms (work fine with oriented-area problems)
- Varifolds: Radon measures on $\mathbb{R}^d \times \text{Grassmann}$ manifold of all unoriented hyperplanes (work fine with curvature problems)

Intermezzo: are generalized surfaces really necessary?



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Working with currents: compactness but no curvature

Given a smooth surface S the canonical current associated to S is given by

$$\langle S, \omega \rangle := \int_S \langle \omega, \eta \rangle d\sigma, \quad \eta \text{ orientation on } S$$

- Compactness holds true if we have a bound on the area

For our problem we have compactness of the currents S_ε , but we do not have a good notion of curvature of a current

Working with varifolds: curvature but no compactness

Given a smooth surface S the canonical varifold associated to S is given by

$$\langle V_S, \psi \rangle := \int_S \psi(x, T_x S) d\sigma, \quad \psi \in C_c^0(\mathbb{R}^3 \times G(2,3))$$

- We have a good notion of a second fundamental form of a varifold (hence good notions of mean curvature and gaussian curvature)
- Compactness holds true if we have a bound on the second fundamental form

For our problem the bound

$$G_\varepsilon(u_\varepsilon, v_\varepsilon) \leq c$$

does not provide a bound on the second fundamental form of the varifold V_{S_ε} since θ_ε is not orthogonal to S_ε



Working with Gauss graphs

Exploiting the estimate

$$c \geq G_\varepsilon(u_\varepsilon, v_\varepsilon) \geq \int_{S_\varepsilon} \frac{1}{4}(\lambda_\varepsilon^{(1)} + \lambda_\varepsilon^{(2)})^2 - \frac{1}{6}\lambda_\varepsilon^{(1)}\lambda_\varepsilon^{(2)} d\sigma$$

it is relatively easy to realize that the area of

$$G_\varepsilon := \{(p, \theta_\varepsilon(p)) : p \in S_\varepsilon\}$$

remains bounded. When $\varepsilon \sim 0$ the area of G_ε should be the area of the graph of the Gauss map on S . In the area of the graph of the Gauss map are encoded informations on the curvature of S : the idea is therefore to consider the currents

$$G_\varepsilon$$

Generalized Gauss graphs (Anzellotti-Serapioni-Tamanini, Indiana 1990)

If T is a Generalized Gauss graph, that is a limit, as a current, of Gauss graphs of smooth surfaces, then:

- T is an integer rectifiable current, i.e.

$$\langle T, \omega \rangle = \int_R \langle \omega, \eta \rangle \beta \, d\sigma, \quad R \text{ rectifiable, } \eta \text{ orientation on } R,$$

$$\beta: R \rightarrow \mathbb{Z}$$

- Up to \mathcal{H}^2 -negligible sets, R is a countable union of Gauss graphs of smooth and orientable surfaces
- There exists a stable notion of principal curvatures of T

Back to compactness and liminf

- The estimate

$$G_\varepsilon(u_\varepsilon, v_\varepsilon) \gtrsim \int_{S_\varepsilon} \frac{1}{4}(\lambda_\varepsilon^{(1)} + \lambda_\varepsilon^{(2)})^2 - \frac{1}{6}\lambda_\varepsilon^{(1)}\lambda_\varepsilon^{(2)} d\sigma$$

says that the area of G_ε is bounded

- When $\varepsilon \rightarrow 0$ the transport rays θ_ε tend to be normal, therefore

$$T_{G_\varepsilon} \rightarrow \text{Generalized Gauss graph}$$

- Thanks to the stability of principal curvatures it is possible to pass to the limit in

$$\int_{S_\varepsilon} \frac{1}{4}(\lambda_\varepsilon^{(1)} + \lambda_\varepsilon^{(2)})^2 - \frac{1}{6}\lambda_\varepsilon^{(1)}\lambda_\varepsilon^{(2)} d\sigma$$

Further investigations

- Complete the Γ -lim inf inequality
- Biological structure of limits currents/varifolds
- Higher codimension
- Local minimizers of F_ε (recent papers by Buttazzo et al.)
- Try to minimize directly the Helfrich functional on generalized Gauss graphs (with M. Morandotti)
- Local minimizers/critical points of Helfrich?
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Thank you!

