

JOURNAL OF

Geometry and Symmetry in Physics

ISSN 1312-5192

ON THE GEOMETRY OF SO(3)

ABDIGAPPAR NARMANOV and SHOHIDA ERGASHOVA

Communicated by Andreas Arvanitoyeorgos

The geometry of the rotation group SO(3) is of interest in many areas of mathematics and mechanics, and many papers are devoted to the study of this group. In the first part of this paper, the geometry of a known submersion on the rotation group with a base on a two-dimensional sphere is studied. It is proved that this submersion is Riemannian and generates a totally geodesic Riemannian foliation. In the second part of the paper, the geometry of the Liouville foliation on the cotangent bundle $T^*SO(3)$ of the group SO(3) generated by a completely integrable Hamiltonian system is studied. It is shown that the regular leaf of this foliation is a three-dimensional surface of non-zero normal curvature and zero Gaussian torsion.

MSC: 53C12, 57R30 *Keywords*: Foliation, Hamiltonian system, Killing field, quaternion, Riemannian submersion, rotation group

Contents

1	Introduction	83
2	Riemannian Submersion on SO(3)	86
3	Hamiltonian Systems on $T^* \mathbb{SO}(3)$	88
4	Conclusions	93
References		93

1. Introduction

Let *M* be a smooth Riemannian manifold of dimension *n* with the Riemannian metric *g*, ∇ be the Levi-Civita connection, and $\langle \cdot, \cdot \rangle$ be the inner product defined by the Riemannian metric *g*.

doi: 10.7546/jgsp-72-2025-83-94